Metaheuristics Summer School.

David Salinas, Freiburg University. July 2024.

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How to select which restaurant to go?



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- Which configuration to pick? •





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- If one configuration is worse for all metrics than another configurations, it is **dominated**
- The set of non dominated options is the **Pareto front** $\mathscr{P}(y)$







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Multiobjective landscape



Multiobjective landscape

- Our focus for this lecture is on blackbox multiobjective optimization
- Related areas:
 - Multiobjective RL: optimize an RL for multiple objective (eg a robot that minimize rewards and keep energy down)
 - Constrained optimization when constraint is known a priori (optimise while penalizing the constraint violation)
 - Multivariate analysis (Time series forecasting, causal analysis ...)











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- Conclusion





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How to extend to multiple objectives?

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- The hypervolume is the most common metric



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 $HV(\mathscr{P}(f)) - HV(\{f(x_1), \dots, f(x_n)\})$

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This transformation makes the comparisons invariant through any monotonic change! Neat 👍 [Binois 2020]

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 - Others: Population Based Training, Multi-fidelity







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0.4

 $f_1(x)$

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Simplest scalarization: $g(x) = \sum_{i=1}^{d} w_i f_i(x) = w^T f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \forall i$)

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Computer vision models plotted by accuracy (\uparrow) and throughput (\uparrow)

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Computer vision models plotted by accuracy (\uparrow) and throughput (\uparrow)



But linear scalarization is still limiting, need to find weights, no general guarantee

• Chebychev scalarization: $\max_{i=1..d} w_i |f_i(x) - z_i^*|$

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Decomposition based (MOEA/D): decomposes into subregions of the Pareto



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Figure 3: Illustration of non-dominated sorting. The layers show the partitioning of the data in Pareto fronts. The numbers depict the overall rank by computing the ϵ -net within each layer.

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Continue training the networks

Multi-Objective Population Based Training [Dushatskiy 2023]

NSGA-II

- Initialise population $X_n \subset \mathcal{X}^n$ of *n* configurations ullet
- While not converged: ullet
 - $X = mutate-and-combine(X_n)$ // gets many candidates, possibly more than n
 - X = non-dominated-sort(X) // sort them in a multiobjective way
 - $X_n = X[:n]$ // keep top *n* candidates



Continue training the networks

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GPareto [Binois 2019]

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Name	Indicator	Analytical	m	Cost	$\begin{array}{c} {\rm Scaling} \\ {\rm dependent} \end{array}$
crit_EHI	Hypervolume	m = 2 only	Any	+ to +++	Yes
$crit_EMI$	$\text{Additive-}\epsilon$	No	Any	++	Yes
$crit_SMS$	Hypervolume	Yes	Any	+	Yes
crit_SUR	Probability of non-domination	No	$m \leq 3$	+++	No

GPareto [Binois 2019]



should be prioritised



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An AB test for many metrics on Facebook. Beyond Loss Efficient Optimization of Living Machine Learning. Bakshi Automl 2023



- should be prioritised
- Preference based methods ask users to provide feedback on which multiobjective solution is better



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- solution is better



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Sometimes, we have many objectives and it is hard to know exactly how they



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Asynchronous Succesful halving (ASHA)



Image credit: Matthias Feurer.

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Great performance in practice and one can use multiple workers

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Multi-objective Asynchronous Successive Halving [Schmucker 2021]





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(b) Sampled configurations on Fashion-MNIST dataset.

Bag of Baselines for Multi-objective Joint Neural Architecture Search and Hyperparameter Optimization [Guererro Viu 2021]







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Tune by having a population of candidates





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SO: accuracy

0.2 0.4 0.6 0.8

accuracy

vopustness 0.2

0.0

Precision/Recall, Higgs







precision



0.0 0.2 0.4 0.6 0.8 1.0 precision



0.2 0.4 0.6 0.8 1.0

MO-PBT



0.2 0.4 0.6 0.8 accuracy

0.0 0.2 0.4 0.6 0.8

SO: recall

precision

SO: robustness

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accuracy

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accuracy

precision



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Accuracy/Robustness, CIFAR-10 max. scalarization



accuracy

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Good at distributing exploration on the Pareto Front

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Some theoretical foundations

Some theoretical foundations

- Computational complexity of multiobjective quantities
- Regret bounds on scalarization methods
- Difficulties of high-dimensional multiobjective optimization
- Link with multivariate analysis and Copula





• If P \neq NP then the hypervolume cannot be computed in polynomial time [Bringmann 2013]

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- Digest of computational results: https://hpi.de/friedrich/research/the-hypervolume-indicator.html





Theoretical foundations of multiobjective optimization Regret bounds

Random Hypervolume Scalarizations for Provable Multi-Objective Black Box Optimization [Golovin 2020]



Theoretical foundations of multiobjective optimization Regret bounds

• Recall Golovin scalarization: $s_{\lambda}(y) = \min(\max(0, y_i/\lambda_i))^k)$

i=1 k

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Lemma 5 (Hypervolume as Scalarization). Let $Y = \{y_1, ..., y_m\}$ be a set of m points in \mathbb{R}^k . Then, the hypervolume of Y with respect to a reference point z is given by:

$$\mathcal{HV}_{z}(Y) = c_{k}\mathbb{E}_{\lambda \sim \mathcal{S}^{k-1}_{+}}\left[\max_{y \in Y} s_{\lambda}(y-z)\right]$$

where $s_{\lambda}(y) = \min_{i} (\max(0, y_i/\lambda_i))^k$ and $c_k = \frac{\pi^{k/2}}{2^k \Gamma(k/2+1)}$ is a dimension-independent constant.

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This scalarization allows to approximate the hypervolume given many weights λ sampled on a sphere



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Furthermore, $\mathcal{HV}_z(Y_T) \geq \mathcal{HV}_z(Y^*) - \epsilon_T$, where $\epsilon_T = O(k^2 n^{1/2} [\gamma_T \ln(T)/T]^{1/2})$.

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Random Hypervolume Scalarizations for Provable Multi-Objective Black Box Optimization [Golovin 2020]

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Informal statement, the average Hypervolume regret obtained with Bayesian Optimization goes to zero







What about optimizing many objectives?





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For instance, the probability that a point is non-dominated in a uniformly distributed set of sample points grows exponentially fast towards 1 with the number of objectives. [Emmerich 2018]



Theoretical foundations of multiobjective optimization Link with Copula theory





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Figure 2: Level lines ∂L^F_{α} with $\alpha = 0.0001, 0.01, 0.1$ of the empirical cumulative distribution function of f(X) obtained with sampled points (in black), showing the link between the level line of level α and the Pareto front \mathcal{P} (apart from the vertical and horizontal components), as α tends to zero.



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Copula are central in multivariate analysis



Link with Copula theory

Sklar theorem

For any continuous multivariate distribution function F_{Y} , there exists a unique Copula function C such that: $F_{Y}(y_{1},...,y_{d}) = C(F_{1}(y_{1}),...,F_{d}(y_{d}))$

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Figure 12: Levels lines $\partial L_{\alpha}^{C_{\phi}}$ of the different fitted Archimedean models based on the pseudo-data \mathbf{U}^{k} , $k = 1, \ldots, n$, from test problem Poloni. The level lines L_{α}^{C} correspond in each case to α^* , 0.1, 0.2, 0.3 and 0.4.

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Applications & use cases

Applications Hardware-aware NAS
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Error and latency for time series forecasting models

- Assume we have access to offline evaluations... ullet

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task	model	learning-rate	#layers	error	latency
electricity	DeepAR	0.001	10	0.1	22.0
electricity	electricity Transformer		10	0.08	2.5
electricity Transformer		1.0	2	0.9	0.2
traffic	DeepAR	0.1	2	0.9	0.2
traffic	Transformer	0.004	2.5	0.03	2.2

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- 3. Predict objectives on the new task on all untrained models

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electricity	Transformer	0.001	10	-1.2	0.6
electricity Transformer		1.0	2	1.5	-2.3
traffic	DeepAR	0.1	2	2.2	-2.4
traffic	Transformer	0.004	2.5	-1.4	0.5

- Assume we have access to offline evaluations...
- 1. Normalize each objective and task with $\psi = \Phi^{-1} \circ F$
- 2. Fit *d* independent predictive models for each objectives $[z_1(x), \ldots, z_d(x)]$
- 3. Predict objectives on the new task on all untrained models

tas	k model	learning-rate	#layers	$z_{ m error}$	$z_{latency}$
sola	r DeepAR	0.001	10	?	?
sola	r Transformer	0.001	10	?	?
sola	r Transformer	1.0	2	?	?
sola	r DeepAR	0.1	2	?	?
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_	task	model	learning-rate	#layers	$z_{ m error}$	$z_{latency}$		Dradia
_	solar	DeepAR	0.001	10	?	?	_	Freuic
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	solar	Transformer	1.0	2	?	?		_
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 task solar solar	model DeepAR Transformer	learning-rate 0.001 0.001	#layers 10 10	<i>z</i> _{error} 0.2 -1.2	z _{latency} 3.4 0.6	-	Predic each
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latency

Multiobjective transfer learning Zeroshot prediction of Pareto front through transfer learning



Example of one zero-shot selection in a fixed task

Average performance on all tasks

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Applications: Instance Recommendation


• Instance recommendation for model deployment



- Instance recommendation for model deployment •
- Recommend endpoint configuration (machine type, • number of OMP thread, ...) given a ML model

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 - Throughput
 - Cost per hour
- Ideally, wants to get recommendation eg zeroshot recommendations

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Average time for 10000 batches (seconds)









DeepAR time vs cost for 10000 batch (2 layers, 40 cells)











m5: 4 CPUs machine c5.4x: 16 CPUs machine g4dn.16x: 64 CPUs machine with one GPU (T4) p3.2x: 8 CPU machines with V100 GPU

If we have some metadata on the model being used (reset, XGboost, ...). Can we predict the Pareto front of hardware configurations?



I have an XGBoost model, what machine should I use to deploy it?

Sample many ML model and measure latency and cost on multiple machine

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Predict latency and cost for each machine type given metadata x using $\Phi_{\theta}(x,m) \in \mathbb{R}^2$





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Rank★ (UB)	Model A	Arena Score 🔺	95% CI 🔺	Votes 🔺	Organization	License
1	GPT-40-2024-05-13	1287	+3/-3	56905	OpenAI	Proprietary
2	Claude 3.5 Sonnet	1272	+4/-4	24913	Anthropic	Proprietary
2	Gemini-Advanced-0514	1267	+3/-3	42981	Google	Proprietary
3	Gemini-1.5-Pro-API-0514	1262	+3/-3	49828	Google	Proprietary
4	Gemini-1.5-Pro-API-0409- Preview	1258	+3/-3	55567	Google	Proprietary
4	GPT-4-Turbo-2024-04-09	1257	+3/-4	72512	OpenAI	Proprietary
6	GPT-4-1106-preview	1251	+3/-3	86474	OpenAI	Proprietary
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- LLM judge has **many** hyperparameters!
- LLM model (llama3-70B, llama3-8B, GPT4)
- Prompt being used
- Judge LLM inference parameters (temperature & topk)
- Number of LLM samples
- Float precision (FP8, BF16, ...)
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... and **multiple** objectives

- Spearman correlation with ELO ratings
- Dollar cost to evaluate a model



Table 1. Separability and agreement per benchmark.

	Chatbot Arena (English-only)	MT-bench	AlpacaEval 2.0 LC (Length Controlled)	Arena-Hard-Auto-v0.1
Avg #prompts per model eval	10,000+	160	800	1,000
Agreement to Chatbot Arena with 95% Cl	N/A	26. 1%	81.2%	89.1%
Spearman Correlation	N/A	91.3%	90.8%	94.1%
Separability with 95% Cl	85.8%	22.6%	83.2%	87.4%
Real-world	Yes	Mixed	Mixed	Yes
Freshness	Live	Static	Static	Frequent Updates
Eval cost per model	Very High	\$10	\$10	\$25
Judge	Human	LLM	LLM	LLM
*Results based on 20	top models from Chat	bot Arena that are al	so presented on Alpaca	a Eval

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	Chatbot Arena (English-only)	MT-bench	AlpacaEval 2.0 LC (Length Controlled)	Arena-Hard-Auto-v0.1
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Agreement to Chatbot Arena with 95% Cl	N/A	26. 1%	81.2%	89.1%
Spearman Correlation	N/A	91.3%	90.8%	94.1%
Separability with 95% Cl	85.8%	22.6%	83.2%	87.4%
Real-world	Yes	Mixed	Mixed	Yes
Freshness	Live	Static	Static	Frequent Updates
Eval cost per model	Verv Hiah	\$10	\$10	\$25
Judge	al case for	multi-obie	ctive optim	nization!

► *Rest....

Table 1. Separability and agreement per benchmark.

	Chatbot Arena (English-only)	MT-bench	AlpacaEval 2.0 LC (Length Controlled)	Arena-Hard-Auto-v0.1
Avg #prompts per model eval	10,000+	160	800	1,000
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Real-world	Yes	Mixed	Mixed	Yes
Freshness	Live	Static	Static	Frequent Updates
Eval cost per model	Verv Hiah	\$10	\$10	\$25

Judge



► *ResL

Main difficulties to overcome Evaluating one judge configurations is too expensive (10\$ x #models ~ 400\$)

Ideal case for multi-objective optimization!

Two techniques: subselect most informative instructions and use multifidelity



Cost (\$)

llm

- gpt-4o
- meta-llama/Llama-3-70b-chat-hf
- meta-llama/Llama-3-8b-chat-hf
- gpt-3.5-turbo-0125
- gpt4-turbo





Cost (\$)











Code and libraries





GPareto: Gaussian Processes	
	for Pareto Front Estimation and Optimization
This R package provides tools	for multi-objective optimization of expensive
black-box functions along wit	h estimation of Pareto fronts.

This the development version, contributions are welcomed.

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areto			
eto: Gaussian Processes for Pareto Front Estima	ation and Optimization		
R package provides tools for multi-objective (-box functions along with estimation of Paret	GPareto (R	libra	ary)
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README	Code of conduct	MIT license	Ø	≔
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Welcome to PyGMO

PyGMO (the Python Parallel Global Multiobjective Optimizer) is a scientific library providing a large number of optimisation problems and algorithms under the same powerful parallelization abstraction built around the generalized island-model paradigm. What this means to the user is that the available algorithms are all



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GPareto	
Pareto: Gaussian Processes for Pareto Front Es	stimation and Optimization
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BoTorch PyTorch	n is a library for Bay n.	esian Optimization/	on built on



Pygmo (Python/c++)

- General python library
- Contains optimizers but also utilities to compute
- Hypervolume, Hypervolume contribution, ...
- Contains approximation algorithms

Welcome to PyGMO

PyGMO (the Python Parallel Global Multiobjective Optimizer) is a scientific library providing a large number of optimisation problems and algorithms under the same powerful parallelization abstraction built around the *generalized island-model* paradigm. What this means to the user is that the available algorithms are all





Code

How to tune multiple objectives in Syne Tune

Step 1: report multiple objectives in a training script

```
if __name__ == "__main__":
    # plot_function()
    parser = ArgumentParser()
    parser.add_argument("--steps", type=int, required=True)
    parser.add_argument("---theta", type=float, required=True)
    parser.add_argument("--sleep_time", type=float, required=False, default=0.1)
    args, _ = parser.parse_known_args()
    assert 0 <= args.theta < np.pi / 2</pre>
    reporter = Reporter()
    for step in range(args.steps):
        y = f(t=step, theta=args.theta)
        reporter(step=step, **y)
```

https://github.com/syne-tune/syne-tune/blob/main/examples/launch_height_moasha.py

Code

How to tune multiple objectives in Syne Tune

```
Step 2: call a multiobjective optimizer to tune the training script
Step 1: report multiple objectives in a training script
                                                                                                     entry_point = (
if __name__ == "__main__":
                                                                                                         Path(__file__).parent
    # plot_function()
                                                                                                        / "training_scripts"
                                                                                                         / "mo_artificial"
    parser = ArgumentParser()
                                                                                                         / "mo_artificial.py"
    parser.add_argument("--steps", type=int, required=True)
    parser.add_argument("---theta", type=float, required=True)
                                                                                                     mode = "min"
    parser.add_argument("--sleep_time", type=float, required=False, default=0.1)
                                                                                                     np.random.seed(0)
    args, _ = parser.parse_known_args()
                                                                                                     scheduler = MOASHA(
                                                                                                        max_t=max_steps,
    assert 0 <= args.theta < np.pi / 2</pre>
                                                                                                        time_attr="step",
                                                                                                         mode=mode,
    reporter = Reporter()
                                                                                                        metrics=["y1", "y2"],
    for step in range(args.steps):
                                                                                                        config_space=config_space,
         y = f(t=step, theta=args.theta)
                                                                                                     trial_backend = LocalBackend(entry_point=str(entry_point))
         reporter(step=step, **y)
                                                                                                     stop_criterion = StoppingCriterion(max_wallclock_time=20)
                                                                                                     tuner = Tuner(
                                                                                                         trial_backend=trial_backend,
                                                                                                         scheduler=scheduler,
                                                                                                         stop_criterion=stop_criterion,
                                                                                                        n_workers=n_workers,
                                                                                                         sleep_time=0.5,
                                                                                                     tuner.run()
```

https://github.com/syne-tune/syne-tune/blob/main/examples/launch_height_moasha.py

• Multiobjective optimization allows to optimise multiple objectives at the same time



• Multiobjective optimization allows to optimise multiple objectives at the same time • Generally not a single solution but a set of optimal solutions, the Pareto front



- •
- Key methods:

• Multiobjective optimization allows to optimise multiple objectives at the same time Generally not a single solution but a set of optimal solutions, the Pareto front



- Key methods:
 - Scalarization

• Multiobjective optimization allows to optimise multiple objectives at the same time • Generally not a single solution but a set of optimal solutions, the Pareto front



- •
- Key methods:
 - Scalarization
 - **Bayesian Optimization** \bullet

• Multiobjective optimization allows to optimise multiple objectives at the same time Generally not a single solution but a set of optimal solutions, the Pareto front



- •
- Key methods:
 - Scalarization
 - **Bayesian Optimization**
 - Evolution Algorithms

• Multiobjective optimization allows to optimise multiple objectives at the same time Generally not a single solution but a set of optimal solutions, the Pareto front


Conclusion

- Key methods:
 - Scalarization
 - **Bayesian Optimization**
 - Evolution Algorithms
- Many applications!

Multiobjective optimization allows to optimise multiple objectives at the same time Generally not a single solution but a set of optimal solutions, the Pareto front



Conclusion

- Key methods:
 - Scalarization
 - **Bayesian Optimization**
 - Evolution Algorithms
- Many applications!
- Active area of research

Multiobjective optimization allows to optimise multiple objectives at the same time Generally not a single solution but a set of optimal solutions, the Pareto front

