David Salinas, Freiburg University. July 2024.

Multiobjective optimization Metaheuristics Summer School.

-
-
-
-
-
-
-
-
-

• Optimization is often about optimising a single objective but what if we have many?

- Optimization is often about optimising a single objective but what if we have many?
- Assume you want to pick a restaurant close to the Summer school…

- Optimization is often about optimising a single objective but what if we have many?
- Assume you want to pick a restaurant close to the Summer school…

- Optimization is often about optimising a single objective but what if we have many?
- Assume you want to pick a restaurant close to the Summer school…
- And you only care about rating **and** distance

- Optimization is often about optimising a single objective but what if we have many?
- Assume you want to pick a restaurant close to the Summer school…
- And you only care about rating **and** distance

- Optimization is often about optimising a single objective but what if we have many?
- Assume you want to pick a restaurant close to the Summer school…
- And you only care about rating **and** distance

-
-
-
-
-
-
-
- - -
-
-
-
- -
	-
-
- -

• Plot objective observations $y\in\mathbb{R}^{n\times d}$ where n is the number of configurations (restaurants) and d is the number of objectives

• Plot objective observations $y\in\mathbb{R}^{n\times d}$ where n is the number of configurations (restaurants) and d is the number of objectives

• Plot objective observations $y\in\mathbb{R}^{n\times d}$ where n is the number of configurations (restaurants) and d is the number of objectives

- Plot objective observations $y\in\mathbb{R}^{n\times d}$ where n is the number of configurations (restaurants) and d is the number of objectives
- No just a single best solution!

- Plot objective observations $y\in\mathbb{R}^{n\times d}$ where n is the number of configurations (restaurants) and d is the number of objectives
- No just a single best solution!
- \odot Which configuration to pick?

- Plot objective observations $y\in\mathbb{R}^{n\times d}$ where n is the number of configurations (restaurants) and d is the number of objectives
- No just a single best solution!
- Which configuration to pick?
- Some choices are sub-optimal

- Plot objective observations $y\in\mathbb{R}^{n\times d}$ where n is the number of configurations (restaurants) and d is the number of objectives
- No just a single best solution!
- Which configuration to pick?
- Some choices are sub-optimal

- Plot objective observations $y\in\mathbb{R}^{n\times d}$ where n is the number of configurations (restaurants) and d is the number of objectives
- No just a single best solution!
- Which configuration to pick?
- Some choices are sub-optimal

- Plot objective observations $y\in\mathbb{R}^{n\times d}$ where n is the number of configurations (restaurants) and d is the number of objectives
- No just a single best solution!
- Which configuration to pick?
- Some choices are sub-optimal
- If one configuration is worse for all metrics than another configurations, it is **dominated**

- Plot objective observations $y\in\mathbb{R}^{n\times d}$ where n is the number of configurations (restaurants) and d is the number of objectives
- No just a single best solution!
- Which configuration to pick?
- Some choices are sub-optimal
- If one configuration is worse for all metrics than another configurations, it is **dominated**
- The set of non dominated options is the **Pareto front** $\mathscr{P}(y)$

-
-
-
-
-
-
-
- - -

• Metrics observations $y \in \mathbb{R}^{n \times d}$, assume all metrics are to be minimized

- Metrics observations $y \in \mathbb{R}^{n \times d}$, assume all metrics are to be minimized
- We say that y_i dominate y_j (which we denote $y_i \lt y_j$) iff $\forall k, y_{ik} \le y_{jk}$ and $\exists k, y_{ik} \lt y_{jk}$.

- Metrics observations $y \in \mathbb{R}^{n \times d}$, assume all metrics are to be minimized
- We say that y_i dominate y_j (which we denote $y_i \lt y_j$) iff $\forall k, y_{ik} \le y_{jk}$ and $\exists k, y_{ik} \lt y_{jk}$.
- The Pareto front $\mathcal{P}(y)$ is the set of non dominated options $\mathcal{P}(y) = \{y_i | \exists y_j \prec y_i\}$

- Metrics observations $y \in \mathbb{R}^{n \times d}$, assume all metrics are to be minimized
- We say that y_i dominate y_j (which we denote $y_i \lt y_j$) iff $\forall k, y_{ik} \le y_{jk}$ and $\exists k, y_{ik} \lt y_{jk}$.
- The Pareto front $\mathcal{P}(y)$ is the set of non dominated options $\mathcal{P}(y) = \{y_i | \exists y_j \prec y_i\}$
- \bigcirc Which configurations are in the Pareto front $\mathscr{P}(y)$? \bigcirc

- Metrics observations $y \in \mathbb{R}^{n \times d}$, assume all metrics are to be minimized
- We say that y_i dominate y_j (which we denote $y_i \lt y_j$) iff $\forall k, y_{ik} \le y_{jk}$ and $\exists k, y_{ik} \lt y_{jk}$.
- The Pareto front $\mathcal{P}(y)$ is the set of non dominated options $\mathcal{P}(y) = \{y_i | \exists y_j \prec y_i\}$
- \mathbb{G} Which configurations are in the Pareto front $\mathscr{P}(y)$?

- Metrics observations $y \in \mathbb{R}^{n \times d}$, assume all metrics are to be minimized
- We say that y_i dominate y_j (which we denote $y_i \lt y_j$) iff $\forall k, y_{ik} \le y_{jk}$ and $\exists k, y_{ik} \lt y_{jk}$.
- The Pareto front $\mathcal{P}(y)$ is the set of non dominated options $\mathcal{P}(y) = \{y_i | \exists y_j \prec y_i\}$
- \mathbb{G} Which configurations are in the Pareto front $\mathscr{P}(y)$?

- Metrics observations $y \in \mathbb{R}^{n \times d}$, assume all metrics are to be minimized
- We say that y_i dominate y_j (which we denote $y_i \lt y_j$) iff $\forall k, y_{ik} \le y_{jk}$ and $\exists k, y_{ik} \lt y_{jk}$.
- The Pareto front $\mathcal{P}(y)$ is the set of non dominated options $\mathcal{P}(y) = \{y_i | \exists y_j \prec y_i\}$
- \mathbb{G} Which configurations are in the Pareto front $\mathscr{P}(y)$?
- \bigcirc Given objectives $y \in \mathbb{R}^{n \times d}$, can you give a procedure that finds d configurations that are in the Pareto front (y) in $O(d)$?

- Metrics observations $y \in \mathbb{R}^{n \times d}$, assume all metrics are to be minimized
- We say that y_i dominate y_j (which we denote $y_i \lt y_j$) iff $\forall k, y_{ik} \le y_{ik}$ and $\exists k, y_{ik} \lt y_{ik}$.
- The Pareto front $\mathcal{P}(y)$ is the set of non dominated options $\mathcal{P}(y) = \{y_i | \exists y_i \le y_i\}$
- Which configurations are in the Pareto front $\mathscr{P}(y)$?
- Given objectives $y \in \mathbb{R}^{n \times d}$, can you give a procedure that finds d configurations that are in the Pareto front $\mathscr{P}(y)$ in $\mathscr{O}(d)$?

-
-
-
-
-
-
-
- - - -
			-

-
-
-
-
-
-
-
- - - -
			-

-
-
-
-
-
-
-
- - - -
			-

• Multiobjective optimization:

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front
	- Use as few evaluation call as possible given that *f* is expensive!

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front
	- Use as few evaluation call as possible given that *f* is expensive!
	- It allows to provide optimal choices for **a posteriori** decisions (in the least amount of queries)

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front
	- Use as few evaluation call as possible given that *f* is expensive!
	- It allows to provide optimal choices for **a posteriori** decisions (in the least amount of queries)
	- Useful when we dont know the constraint in advance!

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front
	- Use as few evaluation call as possible given that *f* is expensive!
	- It allows to provide optimal choices for **a posteriori** decisions (in the least amount of queries)
	- Useful when we dont know the constraint in advance!
- Recurring application example in ML:

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front
	- Use as few evaluation call as possible given that *f* is expensive!
	- It allows to provide optimal choices for **a posteriori** decisions (in the least amount of queries)
	- Useful when we dont know the constraint in advance!
- Recurring application example in ML:
	- LLM or CV model that trades accuracy to run on a phone with a reasonable latency

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front
	- Use as few evaluation call as possible given that *f* is expensive!
	- It allows to provide optimal choices for **a posteriori** decisions (in the least amount of queries)
	- Useful when we dont know the constraint in advance!
- Recurring application example in ML:
	- LLM or CV model that trades accuracy to run on a phone with a reasonable latency
- Reasonable latency is hard to give in advance, it depends on the accuracy loss => a posteriori decision

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front
	- Use as few evaluation call as possible given that *f* is expensive!
	- It allows to provide optimal choices for **a posteriori** decisions (in the least amount of queries)
	- Useful when we dont know the constraint in advance!
- Recurring application example in ML:
	- LLM or CV model that trades accuracy to run on a phone with a reasonable latency
- Reasonable latency is hard to give in advance, it depends on the accuracy loss => a posteriori decision
- Typical-metrics considered:

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front
	- Use as few evaluation call as possible given that *f* is expensive!
	- It allows to provide optimal choices for **a posteriori** decisions (in the least amount of queries)
	- Useful when we dont know the constraint in advance!
- Recurring application example in ML:
	- LLM or CV model that trades accuracy to run on a phone with a reasonable latency
- Reasonable latency is hard to give in advance, it depends on the accuracy loss => a posteriori decision
- Typical-metrics considered:
	- Accuracy

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front
	- Use as few evaluation call as possible given that *f* is expensive!
	- It allows to provide optimal choices for **a posteriori** decisions (in the least amount of queries)
	- Useful when we dont know the constraint in advance!
- Recurring application example in ML:
	- LLM or CV model that trades accuracy to run on a phone with a reasonable latency
- Reasonable latency is hard to give in advance, it depends on the accuracy loss => a posteriori decision
- Typical-metrics considered:
	- Accuracy
	- Latency

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front
	- Use as few evaluation call as possible given that *f* is expensive!
	- It allows to provide optimal choices for **a posteriori** decisions (in the least amount of queries)
	- Useful when we dont know the constraint in advance!
- Recurring application example in ML:
	- LLM or CV model that trades accuracy to run on a phone with a reasonable latency
- Reasonable latency is hard to give in advance, it depends on the accuracy loss => a posteriori decision
- Typical-metrics considered:
	- Accuracy
	- Latency
	- Fairness

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front
	- Use as few evaluation call as possible given that *f* is expensive!
	- It allows to provide optimal choices for **a posteriori** decisions (in the least amount of queries)
	- Useful when we dont know the constraint in advance!
- Recurring application example in ML:
	- LLM or CV model that trades accuracy to run on a phone with a reasonable latency
- Reasonable latency is hard to give in advance, it depends on the accuracy loss => a posteriori decision
- Typical-metrics considered:
	- Accuracy
	- Latency
	- Fairness
	- Memory consumption

- Multiobjective optimization:
	- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front
	- Use as few evaluation call as possible given that *f* is expensive!
	- It allows to provide optimal choices for **a posteriori** decisions (in the least amount of queries)
	- Useful when we dont know the constraint in advance!
- Recurring application example in ML:
	- LLM or CV model that trades accuracy to run on a phone with a reasonable latency
- Reasonable latency is hard to give in advance, it depends on the accuracy loss => a posteriori decision
- Typical-metrics considered:
	- Accuracy
	- Latency
	- Fairness
	- Memory consumption
	- Energy consumption, …

Multiobjective landscape

Multiobjective landscape

- Our focus for this lecture is on blackbox multiobjective optimization
- Related areas:
	- Multiobjective RL: optimize an RL for multiple objective (eg a robot that minimize rewards and keep energy down)
	- Constrained optimization when constraint is known a priori (optimise while penalizing the constraint violation)
	- Multivariate analysis (Time series forecasting, causal analysis ...)

-
-
-
-
-
-
-

• Problem formation and evaluations metrics ~10 min

- Problem formation and evaluations metrics ~10 min
- Optimization Methods ~30 min

- Problem formation and evaluations metrics ~10 min
- Optimization Methods ~30 min
- Theoretical foundations ~5 min

- Problem formation and evaluations metrics ~10 min
- Optimization Methods ~30 min
- Theoretical foundations ~5 min
- Applications ~15 min

- Problem formation and evaluations metrics ~10 min
- Optimization Methods ~30 min
- Theoretical foundations ~5 min
- Applications ~15 min
- Code and library ~5 min

- Problem formation and evaluations metrics ~10 min
- Optimization Methods ~30 min
- Theoretical foundations ~5 min
- Applications ~15 min
- Code and library ~5 min
- **Conclusion**

-
-
-
-
-
-
-
- - - - - -
- -
	-
	- -
- -
	-
	-
-
-
- -
-
-
- -
	-
	-
-
- -
	-
	- -
		-
		-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-

• Hyperparameter simple setting, find the best hyperparameter of $f(x) \in \mathbb{R}$

• Hyperparameter simple setting, find the best hyperparameter of $f(x) \in \mathbb{R}$

$$
\bullet \ \ x^* = \operatorname{argmin}_{x \in \mathcal{X}} f(x)
$$

• Hyperparameter simple setting, find the best hyperparameter of $f(x) \in \mathbb{R}$

• $f(x)$ can be the accuracy obtained after training a neural network with hyperparameter *x*

$$
\bullet \; x^* = \text{argmin}_{x \in \mathcal{X}} f(x)
$$

• Hyperparameter simple setting, find the best hyperparameter of $f(x) \in \mathbb{R}$

$$
\bullet \ \ x^* = \operatorname{argmin}_{x \in \mathcal{X}} f(x)
$$

- $f(x)$ can be the accuracy obtained after training a neural network with hyperparameter *x*
- $f(x)$ is assumed to be expensive, we want as little sample as possible

• Hyperparameter simple setting, find the hyperparameter of $f(x) \in \mathbb{R}$

$$
\bullet \ \ x^* = \operatorname{argmin}_{x \in \mathcal{X}} f(x)
$$

- $f(x)$ can be the accuracy obtained after training a neural network with hyperparameter *x*
- $f(x)$ is assumed to be expensive, we want as little sample as possible

• Hyperparameter simple setting, find the hyperparameter of $f(x) \in \mathbb{R}$

$$
\bullet \ \ x^* = \operatorname{argmin}_{x \in \mathcal{X}} f(x)
$$

- $f(x)$ can be the accuracy obtained after training a neural network with hyperparameter *x*
- $f(x)$ is assumed to be expensive, we want as little sample as possible

For instance, $x^* = [\textsf{ViT},\!0.2,\!$ Adam, $10^{-4}]$

• Hyperparameter simple setting, find the hyperparameter of $f(x) \in \mathbb{R}$

$$
\bullet \ \ x^* = \operatorname{argmin}_{x \in \mathcal{X}} f(x)
$$

- $f(x)$ can be the accuracy obtained after training a neural network with hyperparameter *x*
- $f(x)$ is assumed to be expensive, we want as little sample as possible

How to extend to multiple objectives? $\qquad \qquad \qquad \qquad \text{For instance, } x^* = \text{[ViT,0.2,Adam,10^{-4}]}$

• Given a function $f: \mathbb{R}^m \to \mathbb{R}^d$ with m input dimensions and d objectives

- Given a function $f: \mathbb{R}^m \to \mathbb{R}^d$ with m input dimensions and d objectives • Approximate the Pareto front in the least amount of iterations
-

- Given a function $f: \mathbb{R}^m \to \mathbb{R}^d$ with m input dimensions and d objectives
- Approximate the Pareto front in the least amount of iterations
- We need a notion of distance to quantify how far we are from the optimal solution to be able to formulate an optimization problem!

- Given a function $f: \mathbb{R}^m \to \mathbb{R}^d$ with m input dimensions and d objectives
- Approximate the Pareto front in the least amount of iterations
- We need a notion of distance to quantify how far we are from the optimal solution to be able to formulate an optimization problem!
- The hypervolume is the most common metric

• Define a reference point $r \in \mathbb{R}^d$

- Define a reference point $r \in \mathbb{R}^d$
- Hypervolume

- Define a reference point $r \in \mathbb{R}^d$
- Hypervolume
	- $HV_r(y) = "volume between r and the Pareto front \mathscr{P}(y) \subset \mathbb{R}^{d_{rr}}$

Hypervolume Measuring multiobjective performance

- Define a reference point $r \in \mathbb{R}^d$
- Hypervolume
	- $HV_r(y) = "volume between r and the Pareto front \mathscr{P}(y) \subset \mathbb{R}^{d_{rr}}$

Hypervolume Measuring multiobjective performance

- Define a reference point $r \in \mathbb{R}^d$
- Hypervolume
	- $HV_r(y) = "volume between r and the Pareto front \mathscr{P}(y) \subset \mathbb{R}^{d_{rr}}$

Hypervolume Measuring multiobjective performance

- Define a reference point $r \in \mathbb{R}^d$
- Hypervolume
	- $HV_r(y) = "volume between r and the Pareto front \mathscr{P}(y) \subset \mathbb{R}^{d_{rr}}$
	- HV_r(y) = $\mathcal{V}(\lbrace q \in \mathbb{R}^d \mid \exists p \in y, p \leq q \text{ and } q \leq r \rbrace)$

-
-
-
-
-
-
-

• Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front with as few samples as possible

- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front with as few samples as possible
- e.g. optimize $(x_1, \ldots, x_n) = \text{argmax}_{(x_1, \ldots, x_n)}$

$$
,...,x_n) \in \mathbb{R}^m
$$
HV($\{f(x_1), ..., f(x_n)\}\$)

- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front with as few samples as possible
- e.g. optimize $(x_1, ..., x_n) = \text{argmax}_{(x_1, ..., x_n)}$
- The reference point is often chosen to be $1_d \in \mathbb{R}^d$ after having normalised the objectives in [0,1]

$$
,...,x_{n}) \in \mathbb{R}^{n} \mathsf{HV}(\{f(x_{1}),...,f(x_{n})\})
$$

 $1_d \in \mathbb{R}^d$

- approximate the Pareto front with as few samples as possible
- e.g. optimize $(x_1, \ldots, x_n) = \text{argmax}_{(x_1, \ldots, x_n)}$
- objectives in [0,1]
- Sometimes we know the Pareto front (or we estimate after having run many

• Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives,

$$
,...,x_{n}) \in \mathbb{R}^{m} \mathsf{HV}(\{f(x_{1}),...,f(x_{n})\})
$$

• The reference point is often chosen to be $1_d \in \mathbb{R}^d$ after having normalised the $1_d \in \mathbb{R}^d$

optimizers), we can then instead say that we *minimize* the *hypervolume error*:

- Given an expensive blackbox function $y = f(x) \in \mathbb{R}^d$ with d objectives, approximate the Pareto front with as few samples as possible
- e.g. optimize $(x_1, \ldots, x_n) = \text{argmax}_{(x_1, \ldots, x_n)}$
- objectives in [0,1]
- Sometimes we know the Pareto front (or we estimate after having run many

 $HV(\mathcal{P}(f)) - HV(\{f(x_1), ..., f(x_n)\})$

$$
,...,x_{n}) \in \mathbb{R}^{m} \mathsf{HV}(\{f(x_{1}),...,f(x_{n})\})
$$

• The reference point is often chosen to be $1_d \in \mathbb{R}^d$ after having normalised the $1_d \in \mathbb{R}^d$

optimizers), we can then instead say that we *minimize* the *hypervolume error*:

$$
\bigg(\bigg)
$$

-
-
-
-
-
-
-
- -

• We typically want objectives to be comparable and at a similar scale

- We typically want objectives to be comparable and at a similar scale
- Several normalisation are often used for the objectives $y \in \mathbb{R}^{n \times d}$:

- We typically want objectives to be comparable and at a similar scale
- Several normalisation are often used for the objectives $y \in \mathbb{R}^{n \times d}$:
	- Min-max normalisation: $z =$

y − *min*(*y*) $max(y) - min(y)$ ∈ [0,1]

- We typically want objectives to be comparable and at a similar scale
- Several normalisation are often used for the objectives $y \in \mathbb{R}^{n \times d}$: $\int_{y^{(1)} \bullet}^{y^{(1)} \bullet}$ • Min-max normalisation: $z =$ *y* − *min*(*y*) ∈ [0,1]
	- $max(y) min(y)$
	- CDF/rank/copula normalisation: $z = F_y(y)$ where F is the empirical CDF

- We typically want objectives to be comparable and at a similar scale
- Several normalisation are often used for the objectives $y \in \mathbb{R}^{n \times d}$:
	- Min-max normalisation: $z =$
	- CDF/rank/copula normalisation: $z = F_y(y)$ where F is the empirical CDF

This transformation makes the comparisons invariant through any monotonic change! Neat \bigoplus [Binois 2020]

$$
\frac{y - min(y)}{max(y) - min(y)} \in [0,1]
$$

• Recall that we want to maximize the Hypervolume under a minimum amount of function evaluations

• Recall that we want to maximize the Hypervolume under a minimum amount of function evaluations

•
$$
(x_1, ..., x_n) = \text{argmax}_{(x_1, ..., x_n) \in \mathbb{R}^m} \text{HV}(\{f(x_1), ..., x_n\})
$$

 $\{f(x_n)\}\$

• Recall that we want to maximize the Hypervolume under a minimum amount of function evaluations

•
$$
(x_1, ..., x_n) = \text{argmax}_{(x_1, ..., x_n) \in \mathbb{R}^m} \text{HV}(\{f(x_1), ..., x_n\})
$$

- Recall that we want to maximize the Hypervolume under a minimum amount of function evaluations
	-
- Main approaches:

- Recall that we want to maximize the Hypervolume under a minimum amount of function evaluations
	-
- Main approaches:
	- Scalarization: scalarize objectives and apply single objective method

- Recall that we want to maximize the Hypervolume under a minimum amount of function evaluations
	-
- Main approaches:
	- Scalarization: scalarize objectives and apply single objective method
	- Evolutionary Algorithms

- Recall that we want to maximize the Hypervolume under a minimum amount of function evaluations
	-
- Main approaches:
	- Scalarization: scalarize objectives and apply single objective method
	- Evolutionary Algorithms
	- Bayesian Optimization

- Recall that we want to maximize the Hypervolume under a minimum amount of function evaluations
	-
- Main approaches:
	- Scalarization: scalarize objectives and apply single objective method
	- Evolutionary Algorithms
	- Bayesian Optimization
	- Preference based

- Recall that we want to maximize the Hypervolume under a minimum amount of function evaluations
	-
- Main approaches:
	- Scalarization: scalarize objectives and apply single objective method
	- Evolutionary Algorithms
	- Bayesian Optimization
	- Preference based
	- Others: Population Based Training, Multi-fidelity

• Recall that $f(x) \in \mathbb{R}^d$ is our function to optimize

- Recall that $f(x) \in \mathbb{R}^d$ is our function to optimize
- weight vector to be defined (for instance) *d* ∑ *i*=1

\n- Simplest scalarization:
$$
g(x) = \sum_{i=1} w_i f_i(x) = w^T f(x) \in \mathbb{R}
$$
 where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \forall i$)
\n

- Recall that $f(x) \in \mathbb{R}^d$ is our function to optimize
- Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \forall i$) *d* ∑ *i*=1
- \leq We can optimize $g(x)$ with any single objective method!

$$
w_i f_i(x) = w^T f(x) \in \mathbb{R} \text{ where } w \in \mathbb{R}^d \text{ is a}
$$

- Recall that $f(x) \in \mathbb{R}^d$ is our function to optimize
- Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \forall i$) *d* ∑ *i*=1
- \leq We can optimize $g(x)$ with any single objective method!
- **Pi** Need to set the weights

$$
w_i f_i(x) = w^T f(x) \in \mathbb{R} \text{ where } w \in \mathbb{R}^d \text{ is a}
$$

- Recall that $f(x) \in \mathbb{R}^d$ is our function to optimize
- Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \forall i$) *d* ∑ *i*=1
- \leq We can optimize $g(x)$ with any single objective method!
- **Pi** Need to set the weights
- **Fig. 1** Impose some restrictions on the shape of the Pareto front

$$
w_i f_i(x) = w^T f(x) \in \mathbb{R} \text{ where } w \in \mathbb{R}^d \text{ is a}
$$

- Recall that $f(x) \in \mathbb{R}^d$ is our function to optimize
- Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \forall i$) *d* ∑ *i*=1
- \leq We can optimize $g(x)$ with any single objective method!
- • **P** Need to set the weights
- \blacklozenge Impose some restrictions on the shape of the Pareto front $\langle \mathcal{E} \rangle$ Which one?

$$
w_i f_i(x) = w^T f(x) \in \mathbb{R} \text{ where } w \in \mathbb{R}^d \text{ is a}
$$

Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \,\forall i$) *d* ∑ *i*=1 $w_i = 1 \,\forall i$

 $w_i f_i(x) = w^T f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$

Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \,\forall i$) *d* ∑ *i*=1 $w_i = 1 \,\forall i$

 $w_i f_i(x) = w^T f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$

Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \,\forall i$) *d* ∑ *i*=1 $w_i = 1 \,\forall i$

$w_i f_i(x) = w^T f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$
Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \,\forall i$) *d* ∑ *i*=1 $w_i = 1 \,\forall i$

We can vary the weights and obtain different part of the Pareto front

$w_i f_i(x) = w^T f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$

Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \,\forall i$) *d* ∑ *i*=1 $w_i = 1 \,\forall i$

 \odot What is a limitation of this method?

$w_i f_i(x) = w^T f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$

Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \,\forall i$) *d* ∑ *i*=1 $w_i = 1 \,\forall i$

We can reach the whole Pareto front if its convex!

$w_i f_i(x) = w^T f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$

 \odot What is a limitation of this method?

Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \,\forall i$) *d* ∑ *i*=1 $w_i = 1 \,\forall i$

0.2

 0.0

0.0

0.2

 0.4

 $r_1(x)$

 0.6

0.8

1.0

We can reach the whole Pareto front if its convex!

$w_i f_i(x) = w^T f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$

 \odot What is a limitation of this method?

Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \,\forall i$) *d* ∑ *i*=1 $w_i = 1 \,\forall i$

We can reach the whole Pareto front if its convex!

$w_i f_i(x) = w^T f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$

1.0 $f_1(x)$

 \odot What is a limitation of this method?

Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \,\forall i$) *d* ∑ *i*=1 $w_i = 1 \,\forall i$

We can reach the whole Pareto front if its convex!

We can vary the weights and obtain different part of the Pareto front

 \odot What is a limitation

$w_i f_i(x) = w^T f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$

Simplest scalarization: $g(x) = \sum w_i f_i(x) = w' f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$ is a weight vector to be defined (for instance $w_i = 1 \,\forall i$) *d* ∑ *i*=1 $w_i = 1 \,\forall i$

We can reach the whole Pareto front if its convex!

We can vary the weights and obtain different part of the Pareto front

 \odot What is a limitation

and evolutionary methods [Emmerich 2018]

$w_i f_i(x) = w^T f(x) \in \mathbb{R}$ where $w \in \mathbb{R}^d$

and another "model-size" objective (latency, number of parameters, …)

• In multiobjective optimization, one often optimize for an "accuracy" objective

- and another "model-size" objective (latency, number of parameters, …)
- In this case, the Pareto front is **convex**

• In multiobjective optimization, one often optimize for an "accuracy" objective

- and another "model-size" objective (latency, number of parameters, …)
- In this case, the Pareto front is **convex** Computer vision models plotted by

• In multiobjective optimization, one often optimize for an "accuracy" objective

accuracy (↑) and throughput (↑)

- and another "model-size" objective (latency, number of parameters, …)
- In this case, the Pareto front is **convex** Computer vision models plotted by

• In multiobjective optimization, one often optimize for an "accuracy" objective

accuracy (↑) and throughput (↑)

If we decrease our constrain on throughput starting from the maximum throughput, the accuracy drops slowly initially

- and another "model-size" objective (latency, number of parameters, …)
- In this case, the Pareto front is **convex** | Computer vision models plotted by

• In multiobjective optimization, one often optimize for an "accuracy" objective

accuracy (↑) and throughput (↑)

If we decrease our constrain on throughput starting from the maximum throughput, the accuracy drops slowly initially

- and another "model-size" objective (latency, number of parameters, …)
- In this case, the Pareto front is **convex** Computer vision models plotted by

• In multiobjective optimization, one often optimize for an "accuracy" objective

accuracy (↑) and throughput (↑)

If we decrease our constrain on throughput starting from the maximum throughput, the accuracy drops slowly initially

۰

Conversely, if we release the constrain from the highest throughput, we get large gains

 But linear scalarization is still limiting, need to find weights, no general guarantee

• Chebychev scalarization: $\max_{i=1} w_i | f_i$ *i*=1..*d*

 $(x) - z_i^*$

• Chebychev scalarization: $\max_{i=1}$ *i*=1..*d* $W_i|f_i$

- Chebychev scalarization: $\max_{i=1} w_i | f_i$ *i*=1..*d*
	- **Can model concave Pareto front**

- Chebychev scalarization: $\max_{i=1} w_i | f_i$ *i*=1..*d*
	- **Can model concave Pareto front**
	- \sqrt{P} No regret bound

- Chebychev scalarization: $\max_{i=1} w_i | f_i$ *i*=1..*d*
	- *Can model concave Pareto front*
	- \rightarrow No regret bound
- Golovin scalarization: $\min_{i=1} \max(0, f)$ *i*=1..*d*

 $(x) - z_i^*$

 $\int_i^{\cdot}(x)/w_i)$ *d*

- Chebychev scalarization: $\max_{i=1} w_i | f_i$ *i*=1..*d*
	- *Can model concave Pareto front*
	- \sqrt{P} No regret bound
- Golovin scalarization: $\min_{i=1} \max(0, f)$ *i*=1..*d*
	- **East Regret bound**

 $(x) - z_i^*$

 $\int_i^{\cdot}(x)/w_i)$ *d*

- Chebychev scalarization: $\max_{i=1} w_i | f_i$ *i*=1..*d*
	- **Can model concave Pareto front**
	- \rightarrow No regret bound
- Golovin scalarization: $\min_{i=1} \max(0, f)$ *i*=1..*d*
	- **E** Regret bound
	- **P** Needs to be able to bound the objectives

 $\int_i^{\cdot}(x)/w_i)$ *d*

-
-
-
-
-
-
-
- -

• Applies/extend Evolutionary Algorithms (EA)

- Applies/extend Evolutionary Algorithms (EA)
- Three main approaches:

- Applies/extend Evolutionary Algorithms (EA)
- Three main approaches:
	- candidates

• Pareto based (NSGA-II): applies EA and uses **non-dominated sort** to sort

• Pareto based (NSGA-II): applies EA and uses **non-dominated sort** to sort

- Applies/extend Evolutionary Algorithms (EA)
- Three main approaches:
	- candidates
	- Indicator based (SMS-EMOA): optimises a set indicator (for instance hypervolume), for instance removes the solution with the smallest hypervolume contribution from the population

• Pareto based (NSGA-II): applies EA and uses **non-dominated sort** to sort

- Applies/extend Evolutionary Algorithms (EA)
- Three main approaches:
	- candidates
	- Indicator based (SMS-EMOA): optimises a set indicator (for instance hypervolume), for instance removes the solution with the smallest hypervolume contribution from the population
	- front, for each applies different scalarization parameters

• Decomposition based (MOEA/D): decomposes into subregions of the Pareto

• Assume we want to minimize all objectives

- Assume we want to minimize all objectives
- How to *rank n* observations $y \in \mathbb{R}^{n \times d}$ when we have $d > 1$ objectives?

- Assume we want to minimize all objectives
- How to *rank n* observations $y \in \mathbb{R}^{n \times d}$ when we have $d > 1$ objectives?
- Non dominated sort (aka onion sort):

- Assume we want to minimize all objectives
- How to *rank n* observations $y \in \mathbb{R}^{n \times d}$ when we have $d > 1$ objectives?
- Non dominated sort (aka onion sort):
	- Compute the Pareto front of *y*, break ties with an heuristic

- Assume we want to minimize all objectives
- How to *rank n* observations $y \in \mathbb{R}^{n \times d}$ when we have $d > 1$ objectives?
- Non dominated sort (aka onion sort):
	- Compute the Pareto front of *y*, break ties with an heuristic

Figure 3: Illustration of non-dominated sorting. The layers show the partitioning of the data in Pareto fronts. The numbers depict the overall rank by computing the ϵ -net within each layer.

- Assume we want to minimize all objectives
- How to *rank n* observations $y \in \mathbb{R}^{n \times d}$ when we have $d > 1$ objectives?
- Non dominated sort (aka onion sort):
	- Compute the Pareto front of *y*, break ties with an heuristic

The numbers depict the overall rank by computing the ϵ -net within each layer.

- Assume we want to minimize all objectives
- How to *rank n* observations $y \in \mathbb{R}^{n \times d}$ when we have $d > 1$ objectives?
- Non dominated sort (aka onion sort):
	- Compute the Pareto front of *y*, break ties with an heuristic
	- Compute the Pareto front of *y*∖ (*y*), break ties with an heuristic

The numbers depict the overall rank by computing the ϵ -net within each layer.
- Assume we want to minimize all objectives
- How to *rank n* observations $y \in \mathbb{R}^{n \times d}$ when we have $d > 1$ objectives?
- Non dominated sort (aka onion sort):
	- Compute the Pareto front of *y*, break ties with an heuristic
	- Compute the Pareto front of *y*∖ (*y*), break ties with an heuristic

- Assume we want to minimize all objectives
- How to *rank n* observations $y \in \mathbb{R}^{n \times d}$ when we have $d > 1$ objectives?
- Non dominated sort (aka onion sort):
	- Compute the Pareto front of *y*, break ties with an heuristic
	- Compute the Pareto front of *y*∖ (*y*), break ties with an heuristic
	- Heuristic choices aims at selecting a subset with a good coverage:

- Assume we want to minimize all objectives
- How to *rank n* observations $y \in \mathbb{R}^{n \times d}$ when we have $d > 1$ objectives?
- Non dominated sort (aka onion sort):
	- Compute the Pareto front of *y*, break ties with an heuristic
	- Compute the Pareto front of *y*∖ (*y*), break ties with an heuristic
	- Heuristic choices aims at selecting a subset with a good coverage:
		- Crowding distance

- Assume we want to minimize all objectives
- How to *rank n* observations $y \in \mathbb{R}^{n \times d}$ when we have $d > 1$ objectives?
- Non dominated sort (aka onion sort):
	- Compute the Pareto front of *y*, break ties with an heuristic
	- Compute the Pareto front of *y*∖ (*y*), break ties with an heuristic
	- Heuristic choices aims at selecting a subset with a good coverage:
		- Crowding distance
		- Epsilon-net

- Assume we want to minimize all objectives
- How to *rank n* observations $y \in \mathbb{R}^{n \times d}$ when we have $d > 1$ objectives?
- Non dominated sort (aka onion sort):
	- Compute the Pareto front of *y*, break ties with an heuristic
	- Compute the Pareto front of *y*∖ (*y*), break ties with an heuristic
	- Heuristic choices aims at selecting a subset with a good coverage:
		- Crowding distance
		- Epsilon-net

•
•

…

Continue training the networks

Multi-Objective Population Based Training [Dushatskiy 2023]

NSGA-II

- Initialise population $X_n \subset \mathcal{X}^n$ of *n* configurations
- While not converged:
	- $X =$ mutate-and-combine (X_n) // gets many candidates, possibly more than n
	- $X =$ non-dominated-sort (X) // sort them in a multiobjective way
	- $X_n = X[:n]$ // keep top *n* candidates

Continue training the networks

Multi-Objective Population Based Training [Dushatskiy 2023]

GPareto [Binois 2019]

• Gaussian Process can be used as surrogate to estimate the function response $f_i(x)$ for any x (with uncertainty), see first lecture of Aaron

- Gaussian Process can be used as surrogate to estimate the function response $f_i(x)$ for any x (with uncertainty), see first lecture of Aaron
- Most multi-objective approaches fits GP on objectives *individually*

- Gaussian Process can be used as surrogate to estimate the function response $f_i(x)$ for any x (with uncertainty), see first lecture of Aaron
- Most multi-objective approaches fits GP on objectives *individually*
	- Some models the objectives jointly by modelling *correlations* between objectives [Wilson 2010, Alvarez 2011]

- Gaussian Process can be used as surrogate to estimate the function response $f_i(x)$ for any x (with uncertainty), see first lecture of Aaron
- Most multi-objective approaches fits GP on objectives *individually*
	- Some models the objectives jointly by modelling *correlations* between objectives [Wilson 2010, Alvarez 2011]
- BO can be extended by considering multi-objective acquisition functions

- Gaussian Process can be used as surrogate to estimate the function response $f_i(x)$ for any x (with uncertainty), see first lecture of Aaron
- Most multi-objective approaches fits GP on objectives *individually*
	- Some models the objectives jointly by modelling *correlations* between objectives [Wilson 2010, Alvarez 2011]
- BO can be extended by considering multi-objective acquisition functions
	- Expected hypervolume improvement (EHI) [Emmerich 2011]: pick configuration that have largest expected hypervolume gain

- Gaussian Process can be used as surrogate to estimate the function response $f_i(x)$ for any x (with uncertainty), see first lecture of Aaron
- Most multi-objective approaches fits GP on objectives *individually*
	- Some models the objectives jointly by modelling *correlations* between objectives [Wilson 2010, Alvarez 2011]
- BO can be extended by considering multi-objective acquisition functions
	- Expected hypervolume improvement (EHI) [Emmerich 2011]: pick configuration that have largest expected hypervolume gain
	- Expected maximin improvement (EMI) [Svenson 2016]: pick configuration that has largest expected maximin improvement

- Gaussian Process can be used as surrogate to estimate the function response $f_i(x)$ for any x (with uncertainty), see first lecture of Aaron
- Most multi-objective approaches fits GP on objectives *individually*
	- Some models the objectives jointly by modelling *correlations* between objectives [Wilson 2010, Alvarez 2011]
- BO can be extended by considering multi-objective acquisition functions
	- Expected hypervolume improvement (EHI) [Emmerich 2011]: pick configuration that have largest expected hypervolume gain
	- Expected maximin improvement (EMI) [Svenson 2016]: pick configuration that has largest expected maximin improvement

- Gaussian Process can be used as surrogate to estimate the function response $f_i(x)$ for any x (with uncertainty), see first lecture of Aaron
- Most multi-objective approaches fits GP on objectives *individually*
	- Some models the objectives jointly by modelling *correlations* between objectives [Wilson 2010, Alvarez 2011]
- BO can be extended by considering multi-objective acquisition functions
	- Expected hypervolume improvement (EHI) [Emmerich 2011]: pick configuration that have largest expected hypervolume gain
	- Expected maximin improvement (EMI) [Svenson 2016]: pick configuration that has largest expected maximin improvement
	- S-metric selection EGO (SMS) [Poinweiser 2008]: pick configuration that maximises hyper volume according to lower confidence bound

- Gaussian Process can be used as surrogate to estimate the function response $f_i(x)$ for any x (with uncertainty), see first lecture of Aaron
- Most multi-objective approaches fits GP on objectives *individually*
	- Some models the objectives jointly by modelling *correlations* between objectives [Wilson 2010, Alvarez 2011]
- BO can be extended by considering multi-objective acquisition functions
	- Expected hypervolume improvement (EHI) [Emmerich 2011]: pick configuration that have largest expected hypervolume gain
	- Expected maximin improvement (EMI) [Svenson 2016]: pick configuration that has largest expected maximin improvement
	- S-metric selection EGO (SMS) [Poinweiser 2008]: pick configuration that maximises hyper volume according to lower confidence bound
	- Stepwise uncertainty reduction (SUR) [Picheny 2015]: pick configuration that has largest proba of non-domination

- Gaussian Process can be used as surrogate to estimate the function response $f_i(x)$ for any x (with uncertainty), see first lecture of Aaron
- Most multi-objective approaches fits GP on objectives *individually*
	- Some models the objectives jointly by modelling *correlations* between objectives [Wilson 2010, Alvarez 2011]
- BO can be extended by considering multi-objective acquisition functions
	- Expected hypervolume improvement (EHI) [Emmerich 2011]: pick configuration that have largest expected hypervolume gain
	- Expected maximin improvement (EMI) [Svenson 2016]: pick configuration that has largest expected maximin improvement
	- S-metric selection EGO (SMS) [Poinweiser 2008]: pick configuration that maximises hyper volume according to lower confidence bound
	- Stepwise uncertainty reduction (SUR) [Picheny 2015]: pick configuration that has largest proba of non-domination

GPareto [Binois 2019]

-
-
-
-
-
-
-
- - -

• Sometimes, we have many objectives and it is hard to know exactly how they

should be prioritised

• Sometimes, we have many objectives and it is hard to know exactly how they

should be prioritised

• Sometimes, we have many objectives and it is hard to know exactly how they

- should be prioritised
- Preference based methods ask users to provide feedback on which multiobjective solution is better

• Sometimes, we have many objectives and it is hard to know exactly how they

- should be prioritised
- solution is better

• Preference based methods ask users to provide feedback on which multiobjective

• Sometimes, we have many objectives and it is hard to know exactly how they

- should be prioritised
- solution is better

• Preference based methods ask users to provide feedback on which multiobjective

• Sometimes, we have many objectives and it is hard to know exactly how they

- should be prioritised
- solution is better

• Preference based methods ask users to provide feedback on which multiobjective

• Sometimes, we have many objectives and it is hard to know exactly how they

- should be prioritised
- solution is better

• Preference based methods ask users to provide feedback on which multiobjective

• Sometimes, we have many objectives and it is hard to know exactly how they

- should be prioritised
- solution is better

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

100%

• Typically, models are trained incrementally: can we stop bad configuration early?

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)
Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

Great performance in practice and one can use multiple workers

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

- **Great performance** in practice and one can use multiple workers
- \odot How can we extend the algorithm to handle multiple objectives?

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

- **Great performance** in practice and one can use multiple workers
- \odot How can we extend the algorithm to handle multiple objectives?
- \odot We need to sort to discard the bottom half of configurations, how can we sort if we have multiple objectives?

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)

Asynchronous Succesful halving (ASHA)

Image credit: Matthias Feurer.

- **Great performance** in practice and one can use multiple workers
- \odot How can we extend the algorithm to handle multiple objectives?
- \odot We need to sort to discard the bottom half of configurations, how can we sort if we have multiple objectives?

Non-dominated sort allows to sort e when we have multiple objectives

- Typically, models are trained incrementally: can we stop bad configuration early?
- Early results (epochs) can be used to stop bad runs (early stopping)

Multi-objective Asynchronous Successive Halving [Schmucker 2021]

Multi-objective Asynchronous Successive Halving [Schmucker 2021]

Multi-objective Asynchronous Successive Halving [Schmucker 2021]

(b) Sampled configurations on Fashion-MNIST dataset.

Bag of Baselines for Multi-objective Joint Neural Architecture Search and Hyperparameter Optimization [Guererro Viu 2021]

Multi-objective Asynchronous Successive Halving [Schmucker 2021]

Bag of Baselines for Multi-objective Joint Neural Architecture Search and Hyperparameter Optimization [Guererro Viu 2021]

(b) Sampled configurations on Fashion-MNIST dataset.

Bag of Baselines for Multi-objective Joint Neural Architecture Search and Hyperparameter Optimization [Guererro Viu 2021]

• Tune by having a population of candidates

- Tune by having a population of candidates
- When performing mutation, reuse previous weights!

- Tune by having a population of candidates
- When performing mutation, reuse previous weights!
- Allows to learn learning rate schedule!

- Tune by having a population of candidates
- When performing mutation, reuse previous weights!
- Allows to learn learning rate schedule!

- Tune by having a population of candidates
- When performing mutation, reuse previous weights!
- Allows to learn learning rate schedule!

- Tune by having a population of candidates
- When performing mutation, reuse previous weights:
- Allows to learn learning rate schedule!

\odot How can we extend the algorithm to handle multiple objectives?

-
-
-

-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
-
- -

• Multiobjective Population Based Training: uses non-dominated sort with PBT

• Multiobjective Population Based Training: uses non-dominated sort with PBT

-
- Extend PBT to multi objectives

• Multiobjective Population Based Training: uses non-dominated sort with PBT

-
- Extend PBT to multi objectives

precision

 $0.0 0.2 0.4 0.6 0.8$ precision

Precision/Recall, Higgs

 $0.4\,0.6\,0.8\,1.0$ precision

random scalarization

0.0 0.2 0.4 0.6 0.8 1.0 precision

0.0 0.2 0.4 0.6 0.8 1.0 precision

MO-PBT

 0.2 0.4 0.6 0.8 accuracy

Accuracy/Robustness, CIFAR-10

SO: robustness

accuracy

 0.2 0.4 0.6 0.8 accuracy

 0.2 0.4 0.6 0.8

max. scalarization

 0.2 0.4 0.6 0.8 accuracy

random scalarization

 0.2 0.4 0.6 0.8 accuracy

• Multiobjective Population Based Training: uses non-dominated sort with PBT

-
- Extend PBT to multi objectives

precision

SO: accuracy

 0.2 0.4 0.6 0.8

accuracy

robustness
0.2
0.2

 0.0

 $0.0 0.2 0.4 0.6 0.8$ precision

 0.2 0.4 0.6 0.8

accuracy

Precision/Recall, Higgs

precision

random scalarization

0.2 0.4 0.6 0.8 1.0 precision

MO-PBT

0.0 0.2 0.4 0.6 0.8 1.0 precision

MO-PBT

 0.2 0.4 0.6 0.8 accuracy

Good at distributing exploration on the Pareto Front

Accuracy/Robustness, CIFAR-10

 0.2 0.4 0.6 0.8 accuracy

random scalarization

 0.2 0.4 0.6 0.8 accuracy

• Multiobjective Population Based Training: uses non-dominated sort with PBT

-
- Extend PBT to multi objectives

precision

SO: accuracy

 0.2 0.4 0.6 0.8

accuracy

robustness
0.2
0.2

 0.0

 $0.0 0.2 0.4 0.6 0$ precision

 0.2 0.4 0.6

accuracy

 0.8

Precision/Recall, Higgs

precision

random scalarization

0.2 0.4 0.6 0.8 precision

MO-PBT

 0.0 0.2 0.4 0.6 0.8 1.0 precision

1.0

MO-PBT

 0.2 0.4 0.6 0.8 accuracy

Good at distributing exploration on the Pareto Front

Accuracy/Robustness, CIFAR-10

 0.2 0.4 0.6 0.8 accuracy

random scalarization

 0.2 0.4 0.6 0.8 accuracy

• Multiobjective Population Based Training: uses non-dominated sort with PBT

-
- Extend PBT to multi objectives

precision

SO: accuracy

 0.2 0.4 0.6 0.8

accuracy

robustness
co.2
co.2

 0.0

precision

 0.2 0.4 0.6

accuracy

 0.8

Precision/Recall, Higgs

precision

random scalarization

 0.4 0.6 0.8 precision

MO-PBT

 0.0 0.2 0.4 0.6 0.8 1.0 precision

1.0

MO-PBT

 0.2 0.4 0.6 0.8 accuracy

Good at distributing exploration on the Pareto Front

Accuracy/Robustness, CIFAR-10

 0.2 0.4 0.6 0.8 accuracy

random scalarization

 0.2 0.4 0.6 0.8 accuracy

Some theoretical foundations

Some theoretical foundations

- Computational complexity of multiobjective quantities
- Regret bounds on scalarization methods
- Difficulties of high-dimensional multiobjective optimization
- Link with multivariate analysis and Copula

• If $P \neq NP$ then the hypervolume cannot be computed in polynomial time [Bringmann 2013]

- If $P \neq NP$ then the hypervolume cannot be computed in polynomial time [Bringmann 2013]
- Assuming exponential hypothesis, the hypervolume of n points with d objectives can only be $computed$ in $n^{\Omega(d)}$ [Bringmann 2013]

- If $P \neq NP$ then the hypervolume cannot be computed in polynomial time [Bringmann 2013]
- Assuming exponential hypothesis, the hypervolume of n points with d objectives can only be $computed$ in $n^{\Omega(d)}$ [Bringmann 2013]
- However, approximations of the hypervolume can be computed in polynomial time [Bringmann 2010], implementations exists in *Pygmo*

- If $P \neq NP$ then the hypervolume cannot be computed in polynomial time [Bringmann 2013]
- Assuming exponential hypothesis, the hypervolume of n points with d objectives can only be $computed$ in $n^{\Omega(d)}$ [Bringmann 2013]
- However, approximations of the hypervolume can be computed in polynomial time [Bringmann 2010], implementations exists in *Pygmo*
- Digest of computational results: https://hpi.de/friedrich/research/the-hypervolume-indicator.html

Theoretical foundations of multiobjective optimization Regret bounds

Random Hypervolume Scalarizations for Provable Multi-Objective Black Box Optimization [Golovin 2020]

Theoretical foundations of multiobjective optimization Regret bounds

• Recall Golovin scalarization: $s_{\lambda}(y) = \min_{i=1}^{n} (\max(0, y_i/\lambda_i))$

$i=1..k$ *k*)

Random Hypervolume Scalarizations for Provable Multi-Objective Black Box Optimization [Golovin 2020]

Theoretical foundations of multiobjective optimization Regret bounds

• Recall Golovin scalarization: $s_{\lambda}(y) = \min_{i=1}^{n} (\max(0, y_i/\lambda_i))$

Lemma 5 (Hypervolume as Scalarization). Let $Y = \{y_1, ..., y_m\}$ be a set of m points in \mathbb{R}^k . Then, the hypervolume of Y with respect to a reference point z is given by:

$$
{\mathcal{HV}}_z(Y)=c_k\mathbb{E}_{\lambda\sim{\mathcal{S}}^{k-1}_+}\left[\max_{y\in Y}s_\lambda(y-z)\right]
$$

where $s_{\lambda}(y) = \min_{i} (\max(0, y_i/\lambda_i))^k$ and $c_k = \frac{\pi^{k/2}}{2^k \Gamma(k/2+1)}$ is a dimension-independent constant.

 $i=1..k$ *k*)

Random Hypervolume Scalarizations for Provable Multi-Objective Black Box Optimization [Golovin 2020]

• Recall Golovin scalarization: $s_{\lambda}(y) = \min_{i=1}^{n} (\max(0, y_i/\lambda_i))$

Lemma 5 (Hypervolume as Scalarization). Let $Y = \{y_1, ..., y_m\}$ be a set of m points in \mathbb{R}^k . Then, the hypervolume of Y with respect to a reference point z is given by:

$$
{\mathcal{HV}}_z(Y)=c_k\mathbb{E}_{\lambda\sim{\mathcal{S}}^{k-1}_+}\left[\max_{y\in Y}s_\lambda(y-z)\right]
$$

where $s_{\lambda}(y) = \min_{i} (\max(0, y_i/\lambda_i))^k$ and $c_k = \frac{\pi^{k/2}}{2^k \Gamma(k/2+1)}$ is a dimension-independent constant.

 $i=1$ k *k*)

This scalarization allows to approximate the hypervolume given many weights *λ* sampled on a sphere

• Recall Golovin scalarization: $s_\lambda(y) = \min_{i=1}^{\infty}$

Lemma 5 (Hypervolume as Scalarization). Let $Y = \{y_1, ..., y_m\}$ be a set of m points in \mathbb{R}^k . Then, the hypervolume of Y with respect to a reference point z is given by:

$$
{\mathcal{HV}}_z(Y)=c_k\mathbb{E}_{\lambda\sim{\mathcal{S}}^{k-1}_+}\left[\max_{y\in Y}s_\lambda(y-z)\right]
$$

where $s_{\lambda}(y) = \min_{i} (\max(0, y_i/\lambda_i))^k$ and $c_k = \frac{\pi^{k/2}}{2^k \Gamma(k/2+1)}$ is a dimension-independent constant.

Theorem 7 (Theorem 1 in [PKP18]). Let each objective $f_i(x)$ for $x \in [0,1]^n$ follow a Gaussian distribution with marginal variances bounded by 1 and observation noises $\epsilon_i \sim \mathcal{N}(0, \sigma_i^2)$ are independent with $\sigma_i^2 \leq \sigma^2 \leq$ 1. Let $\gamma_{T,k} \leq \gamma_T$, where $\gamma_{T,k}$ is the MIG for the k-th objective. Running Algorithm 1 with L-Lipschitz scalarizations on either UCB or TS acquisition function produces an expected cumulative regret after T steps that is bounded by:

$$
\mathbb{E}[R_C(T)] = O(Lkn^{1/2}[\gamma_T T \ln(T)]^{1/2})
$$

where the expectation is over choice of λ_t and GP measure.

i=1..*k* $(\max(0, y_i/\lambda_i))$ *k*)

This scalarization allows to approximate the hypervolume given many weights *λ* sampled on a sphere

• Recall Golovin scalarization: $s_\lambda(y) = \min_{i=1}^{\infty}$

Lemma 5 (Hypervolume as Scalarization). Let $Y = \{y_1, ..., y_m\}$ be a set of m points in \mathbb{R}^k . Then, the hypervolume of Y with respect to a reference point z is given by:

$$
{\mathcal{HV}}_z(Y)=c_k\mathbb{E}_{\lambda\sim{\mathcal{S}}^{k-1}_+}\left[\max_{y\in Y}s_\lambda(y-z)\right]
$$

where $s_{\lambda}(y) = \min_{i} (\max(0, y_i/\lambda_i))^k$ and $c_k = \frac{\pi^{k/2}}{2^k \Gamma(k/2+1)}$ is a dimension-independent constant.

Theorem 7 (Theorem 1 in [PKP18]). Let each objective $f_i(x)$ for $x \in [0,1]^n$ follow a Gaussian distribution with marginal variances bounded by 1 and observation noises $\epsilon_i \sim \mathcal{N}(0, \sigma_i^2)$ are independent with $\sigma_i^2 \leq \sigma^2 \leq$ 1. Let $\gamma_{T,k} \leq \gamma_T$, where $\gamma_{T,k}$ is the MIG for the k-th objective. Running Algorithm 1 with L-Lipschitz scalarizations on either UCB or TS acquisition function produces an expected cumulative regret after T steps that is bounded by:

$$
\mathbb{E}[R_C(T)] = O(Lkn^{1/2}[\gamma_T T \ln(T)]^{1/2})
$$

where the expectation is over choice of λ_t and GP measure.

i=1..*k* $(\max(0, y_i/\lambda_i))$ *k*)

This scalarization allows to approximate the hypervolume given many weights *λ* sampled on a sphere

This allows to show that Bayesian Optimization average regret converges to zero

• Recall Golovin scalarization: $s_\lambda(y) = \min_{i=1}^{\infty}$

Lemma 5 (Hypervolume as Scalarization). Let $Y = \{y_1, ..., y_m\}$ be a set of m points in \mathbb{R}^k . Then, the hypervolume of Y with respect to a reference point z is given by:

$$
{\mathcal{HV}}_z(Y)=c_k\mathbb{E}_{\lambda\sim{\mathcal{S}}^{k-1}_+}\left[\max_{y\in Y}s_\lambda(y-z)\right]
$$

where $s_{\lambda}(y) = \min_{i} (\max(0, y_i/\lambda_i))^k$ and $c_k = \frac{\pi^{k/2}}{2^k \Gamma(k/2+1)}$ is a dimension-independent constant.

Theorem 7 (Theorem 1 in [PKP18]). Let each objective $f_i(x)$ for $x \in [0,1]^n$ follow a Gaussian distribution with marginal variances bounded by 1 and observation noises $\epsilon_i \sim \mathcal{N}(0, \sigma_i^2)$ are independent with $\sigma_i^2 \leq \sigma^2 \leq$ 1. Let $\gamma_{T,k} \leq \gamma_T$, where $\gamma_{T,k}$ is the MIG for the k-th objective. Running Algorithm 1 with L-Lipschitz scalarizations on either UCB or TS acquisition function produces an expected cumulative regret after T steps that is bounded by:

$$
\mathbb{E}[R_C(T)] = O(Lkn^{1/2}[\gamma_T T \ln(T)]^{1/2})
$$

where the expectation is over choice of λ_t and GP measure.

Theorem 2 (Convergence of Bayesian Optimization with Hypervolume Scalarization: Informal Restatement of Theorem 8). The cumulative hypervolume regret for using random hypervolume scalarization with UCB or TS after T observations is upper bounded as

$$
\sum_{t=1}^T (\mathcal{HV}_z(Y^*) - \mathcal{HV}_z(Y_t)) \le O(k^2 n^{1/2} [\gamma_T T \ln(T)]^{1/2})
$$

Furthermore, $\mathcal{HV}_z(Y_T) \geq \mathcal{HV}_z(Y^*) - \epsilon_T$, where $\epsilon_T = O(k^2 n^{1/2} [\gamma_T \ln(T)/T]^{1/2})$.

i=1..*k* $(\max(0, y_i/\lambda_i))$ *k*)

This scalarization allows to approximate the hypervolume given many weights *λ* sampled on a sphere

This allows to show that Bayesian Optimization average regret converges to zero

• Recall Golovin scalarization: $s_\lambda(y) = \min_{i=1}^{\infty}$

Lemma 5 (Hypervolume as Scalarization). Let $Y = \{y_1, ..., y_m\}$ be a set of m points in \mathbb{R}^k . Then, the hypervolume of Y with respect to a reference point z is given by:

$$
{\mathcal{HV}}_z(Y)=c_k\mathbb{E}_{\lambda\sim{\mathcal{S}}^{k-1}_+}\left[\max_{y\in Y}s_\lambda(y-z)\right]
$$

where $s_{\lambda}(y) = \min_{i} (\max(0, y_i/\lambda_i))^k$ and $c_k = \frac{\pi^{k/2}}{2^k \Gamma(k/2+1)}$ is a dimension-independent constant.

Theorem 7 (Theorem 1 in [PKP18]). Let each objective $f_i(x)$ for $x \in [0,1]^n$ follow a Gaussian distribution with marginal variances bounded by 1 and observation noises $\epsilon_i \sim \mathcal{N}(0, \sigma_i^2)$ are independent with $\sigma_i^2 \leq \sigma^2 \leq$ 1. Let $\gamma_{T,k} \leq \gamma_T$, where $\gamma_{T,k}$ is the MIG for the k-th objective. Running Algorithm 1 with L-Lipschitz scalarizations on either UCB or TS acquisition function produces an expected cumulative regret after T steps that is bounded by:

$$
\mathbb{E}[R_C(T)] = O(Lkn^{1/2}[\gamma_T T \ln(T)]^{1/2})
$$

where the expectation is over choice of λ_t and GP measure.

Theorem 2 (Convergence of Bayesian Optimization with Hypervolume Scalarization: Informal Restatement of Theorem 8). The cumulative hypervolume regret for using random hypervolume scalarization with UCB or TS after T observations is upper bounded as

$$
\sum_{t=1}^T (\mathcal{HV}_z(Y^*) - \mathcal{HV}_z(Y_t)) \le O(k^2 n^{1/2} [\gamma_T T \ln(T)]^{1/2})
$$

Furthermore, $\mathcal{HV}_z(Y_T) \geq \mathcal{HV}_z(Y^*) - \epsilon_T$, where $\epsilon_T = O(k^2 n^{1/2} [\gamma_T \ln(T)/T]^{1/2})$.

i=1..*k* $(\max(0, y_i/\lambda_i))$ *k*)

This scalarization allows to approximate the hypervolume given many weights *λ* sampled on a sphere

This allows to show that Bayesian Optimization average regret converges to zero

Random Hypervolume Scalarizations for Provable Multi-Objective Black Box Optimization [Golovin 2020]

Informal statement, the average Hypervolume regret obtained with Bayesian Optimization goes to zero

Theoretical foundations of multiobjective optimization Difficulties of high-dimensional multiobjective optimization

Theoretical foundations of multiobjective optimization Difficulties of high-dimensional multiobjective optimization

• What about optimizing many objectives?

Theoretical foundations of multiobjective optimization Difficulties of high-dimensional multiobjective optimization

- What about optimizing many objectives?
	- Hard to visualise problems with more than 3 objectives

- What about optimizing many objectives?
	- Hard to visualise problems with more than 3 objectives
	- If $P \neq NP$, the complexity of the hypervolume indicator computation grows super-polynomially with the number of objectives $(n^{22(d)})$ $n^{\Omega(d)}$

Difficulties of high-dimensional multiobjective optimization

Difficulties of high-dimensional multiobjective optimization

- What about optimizing many objectives?
	- Hard to visualise problems with more than 3 objectives
	- If $P \neq NP$, the complexity of the hypervolume indicator computation grows super-polynomially with the number of objectives $(n^{22(d)})$ $n^{\Omega(d)}$
	- The ratio of non-dominated points increases rapidly with the number of objectives

Difficulties of high-dimensional multiobjective optimization

- What about optimizing many objectives?
	- Hard to visualise problems with more than 3 objectives
	- If $P \neq NP$, the complexity of the hypervolume indicator computation grows super-polynomially with the number of objectives $(n^{22(d)})$ $n^{\Omega(d)}$
	- The ratio of non-dominated points increases rapidly with the number of objectives

For instance, the probability that a point is non-dominated in a uniformly distributed set of sample points grows exponentially fast towards 1 with the number of objectives. [Emmerich 2018]

Theoretical foundations of multiobjective optimization Link with Copula theory

• Given a subset $G \subset \mathbb{R}^d$, the Pareto front $\mathscr P$ is defined by:

- Given a subset $G \subset \mathbb{R}^d$, the Pareto front $\mathscr P$ is defined by:
	- $\mathscr{P} = \{ y \in G \mid \forall z \in G, y \leq z \}$

- Given a subset $G \subset \mathbb{R}^d$, the Pareto front $\mathscr P$ is defined by:
	- \bullet $\mathscr{P} = \{y \in G \mid \forall z \in G, y \leq z\} \prec$ Set of points in G that are not dominated

- Given a subset $G \subset \mathbb{R}^d$, the Pareto front $\mathscr P$ is defined by:
	- $\mathcal{P} = \{ y \in G \mid \forall z \in G, y \leq z \}$
- Link with the multivariate cumulative distribution $F_y(y) = \mathbb{P}[Y \le y]$

Mickaël Binois, Didier Rullière, Olivier Roustant

• Given a subset $G \subset \mathbb{R}^d$, the Pareto front $\mathscr P$ is defined by:

$$
\bullet \mathcal{P} = \{ y \in G \mid \forall z \in G, y \leq z \}
$$

• Link with the multivariate cumulative distribution $F_y(y) = \mathbb{P}[Y \le y]$

$$
\bullet \, y \in \mathcal{P} \Rightarrow F_Y(y) = 0
$$

Mickaël Binois, Didier Rullière, Olivier Roustant

- Given a subset $G \subset \mathbb{R}^d$, the Pareto front $\mathscr P$ is defined by:
	- $\mathcal{P} = \{ y \in G \mid \forall z \in G, y \leq z \}$
- Link with the multivariate cumulative distribution $F_y(y) = \mathbb{P}[Y \le y]$

•
$$
y \in \mathcal{P} \Rightarrow F_Y(y) = 0
$$

\n
\nThe Pareto front belongs to the
\nzero level set of the CDF F_Y

Mickaël Binois, Didier Rullière, Olivier Roustant

- Given a subset $G \subset \mathbb{R}^d$, the Pareto front $\mathscr P$ is defined by:
	- $\mathcal{P} = \{ y \in G \mid \forall z \in G, y \leq z \}$
- Link with the multivariate cumulative distribution $F_y(y) = \mathbb{P}[Y \le y]$

•
$$
y \in \mathcal{P} \Rightarrow F_Y(y) = 0
$$

\n
\nThe Pareto front belongs to the
\nzero level set of the CDF F_Y

Mickaël Binois, Didier Rullière, Olivier Roustant

Figure 2: Level lines ∂L_{α}^{F} with $\alpha = 0.0001, 0.01, 0.1$ of the empirical cumulative distribution function of $f(X)$ obtained with sampled points (in black), showing the link between the level line of level α and the Pareto front P (apart from the vertical and horizontal components), as α tends to zero.

- Given a subset $G \subset \mathbb{R}^d$, the Pareto front $\mathscr P$ is defined by:
	- $\mathcal{P} = \{ y \in G \mid \forall z \in G, y \leq z \}$
- Link with the multivariate cumulative distribution $F_y(y) = \mathbb{P}[Y \le y]$

Figure 2: Level lines ∂L_{α}^{F} with $\alpha = 0.0001, 0.01, 0.1$ of the empirical cumulative distribution function of $f(X)$ obtained with sampled points (in black), showing the link between the level line of level α and the Pareto front P (apart from the vertical and horizontal components), as α tends to zero.

•
$$
y \in \mathcal{P} \Rightarrow F_Y(y) = 0
$$

\n
\nThe Pareto front belongs to the
\nzero level set of the CDF F_Y

Mickaël Binois, Didier Rullière, Olivier Roustant

• Copula are central in multivariate analysis

Link with Copula theory

• Copula are central in multivariate analysis

On the estimation of Pareto fronts from the point of view of copula theory

Mickaël Binois, Didier Rullière, Olivier Roustant

Sklar theorem

Link with Copula theory

• Copula are central in multivariate analysis

On the estimation of Pareto fronts from the point of view of copula theory

Mickaël Binois, Didier Rullière, Olivier Roustant

 $C : [0,1]^d \rightarrow [0,1]$ is d -dimensional copula if C is a joint cumulative distribution function of a d -dimensional random $\bm{\mid}$ vector on the unit cube $[0,1]^d$ with uniform marginals

Sklar theorem

- Copula are central in multivariate analysis
- They allow to decouple the scaling effect on each variable F_i with the effect on the joint distribution

On the estimation of Pareto fronts from the point of view of copula theory

Mickaël Binois, Didier Rullière, Olivier Roustant

 $C : [0,1]^d \rightarrow [0,1]$ is d -dimensional copula if C is a joint cumulative distribution function of a d -dimensional random $\bm{\mid}$ vector on the unit cube $[0,1]^d$ with uniform marginals

Link with Copula theory

Sklar theorem

- Copula are central in multivariate analysis
- They allow to decouple the scaling effect on each variable F_i with the effect on the joint distribution
- The *α*-level lines of C, i.e. $\{u \in [0,1]^d \mid C(u_1, ..., u_d) = \alpha\}$ are denoted ∂L_C^{α}

On the estimation of Pareto fronts from the point of view of copula theory

Mickaël Binois, Didier Rullière, Olivier Roustant

 $C : [0,1]^d \rightarrow [0,1]$ is d -dimensional copula if C is a joint cumulative distribution function of a d -dimensional random $\bm{\mid}$ vector on the unit cube $[0,1]^d$ with uniform marginals

Link with Copula theory

Sklar theorem

Link with Copula theory

- Copula are central in multivariate analysis
- They allow to decouple the scaling effect on each variable F_i with the effect on the joint distribution
- The *α*-level lines of C, i.e. $\{u \in [0,1]^d \mid C(u_1, ..., u_d) = \alpha\}$ are denoted ∂L_C^{α}
- The level lines of the Copula ∂L_C^{α} can be connected to the level lines of the multivariate CDF as follow: *C*

On the estimation of Pareto fronts from the point of view of copula theory

Mickaël Binois, Didier Rullière, Olivier Roustant

 $C : [0,1]^d \rightarrow [0,1]$ is d -dimensional copula if C is a joint cumulative distribution function of a d -dimensional random $\bm{\mid}$ vector on the unit cube $[0,1]^d$ with uniform marginals

Sklar theorem

Link with Copula theory

- Copula are central in multivariate analysis
- They allow to decouple the scaling effect on each variable F_i with the effect on the joint distribution
- The *α*-level lines of C, i.e. $\{u \in [0,1]^d \mid C(u_1, ..., u_d) = \alpha\}$ are denoted ∂L_C^{α}
- The level lines of the Copula ∂L_C^{α} can be connected to the level lines of the multivariate CDF as follow: *C*

•
$$
\partial L_{\alpha}^{F} = \{ (y_1, ..., y_d) = (F_1^{-1}(u_1), ..., F_m^{-1}(u_m)) \in \mathbb{R}^d, u \in \partial L_{\alpha}^{C} \}
$$

On the estimation of Pareto fronts from the point of view of copula theory

Mickaël Binois, Didier Rullière, Olivier Roustant

 $C : [0,1]^d \rightarrow [0,1]$ is d -dimensional copula if C is a joint cumulative distribution function of a d -dimensional random $\bm{\mid}$ vector on the unit cube $[0,1]^d$ with uniform marginals

Sklar theorem

Link with Copula theory

- Copula are central in multivariate analysis
- They allow to decouple the scaling effect on each variable F_i with the effect on the joint distribution
- The *α*-level lines of C, i.e. $\{u \in [0,1]^d \mid C(u_1, ..., u_d) = \alpha\}$ are denoted ∂L_C^{α}
- The level lines of the Copula ∂L_C^{α} can be connected to the level lines of the multivariate CDF as follow: *C*

• In addition to connect fundamental aspect of multivariate analysis, those connection allow to model the Pareto front by modelling Copulas

On the estimation of Pareto fronts from the point of view of copula theory

Mickaël Binois, Didier Rullière, Olivier Roustant

 $C : [0,1]^d \rightarrow [0,1]$ is d -dimensional copula if C is a joint cumulative distribution function of a d -dimensional random $\bm{\mid}$ vector on the unit cube $[0,1]^d$ with uniform marginals

•
$$
\partial L_{\alpha}^{F} = \{ (y_1, ..., y_d) = (F_1^{-1}(u_1), ..., F_m^{-1}(u_m)) \in \mathbb{R}^d, u \in \partial L_{\alpha}^{C} \}
$$

Sklar theorem

Theoretical foundations of multiobjective optimization On the estimation of Pareto fronts from the point of

Link with Copula theory

- distribution
-
- as follow:

• ∂L_{α}^F

 \mathbb{Z}^n on the pseudo-data U^k , $k = 1, ..., n$, from test problem Poloni. The level lines \mathbb{Z}^C_α }
correspond in each case to α^* , 0.1, 0.2, 0.3 and 0.4

Sklar theorem For any continuous multivariate distribution function F_Y , there $exists a 1^{m^2m}$ cand function C and that: *C* Gumbel copula RMSE = 0.0708 $F_Y(y_1,$ Copula are

• In addition to connect fundamental aspect of multivariate analysis, those connection allow to model the Pareto front by modelling Copulas

view of copula theory

Mickaël Binois, Didier Rullière, Olivier Roustant

 $C : [0,1]^d \rightarrow [0,1]$ is d -dimensional copula if C is a joint cumulative distribution function of a d -dimensional random $\bm{\mid}$ vector on the unit cube $[0,1]^d$ with uniform marginals

Link with Copula theory

- Copula are
- distribution
-
- as follow:

• ∂L_{α}^F

 0.0

 \mathbb{Z}^n on the pseudo-data U^k , $k = 1, ..., n$, from test problem Poloni. The level lines \mathbb{Z}^C_α }
correspond in each case to α^* , 0.1, 0.2, 0.3 and 0.4

• In addition to One can model the Copula after having transformed each $\frac{1}{2}$, those connection allow to model the Pa variables with the respective CDF, different modelling options are shown here…

On the estimation of Pareto fronts from the point of view of copula theory

Mickaël Binois, Didier Rullière, Olivier Roustant

 $C : [0,1]^d \rightarrow [0,1]$ is d -dimensional copula if C is a joint cumulative distribution function of a d -dimensional random $\bm{\mid}$ vector on the unit cube $[0,1]^d$ with uniform marginals

Sklar theorem

For any continuous multivariate distribution function F_Y , there $exists a 1^{m^2m}$ cand function C and that: *C* Gumbel copula RMSE = 0.0708 $F_Y(y_1,$

Link with Copula theory

- Copula are
- distribution
-
- as follow:

• ∂L_{α}^F

 \mathbb{Z}^n on the pseudo-data U^k , $k = 1, ..., n$, from test problem Poloni. The level lines \mathbb{Z}^C_α }
correspond in each case to α^* , 0.1, 0.2, 0.3 and 0.4

• In addition to One can model the Copula after having transformed each $\frac{1}{2}$, those connection allow to model the Pa variables with the respective CDF, different modelling options are shown here…

On the estimation of Pareto fronts from the point of view of copula theory

Mickaël Binois, Didier Rullière, Olivier Roustant

0

 $C : [0,1]^d \rightarrow [0,1]$ is d -dimensional copula if C is a joint cumulative distribution function of a d -dimensional random $\bm{\mid}$ vector on the unit cube $[0,1]^d$ with uniform marginals

Figure 13: Estimated level line $\partial L_{\alpha^*}^F$ for the Poloni test problem (green dashed line), compared to the Pareto front approximation from the observation P_n (black line) and the true Pareto front P (violet solid line). Other level lines with levels $0.1, 0.2, 0.3$ and 0.4 are also displayed with thinner lines.

Sklar theorem

For any continuous multivariate distribution function F_Y , there $ext{exists a 1}$ Gumbel copula RMSE = 0.0708 $F_Y(y_1,$

Link with Copula theory

- Copula are
- distribution
-
- as follow:

• ∂L_{α}^F

 \mathbb{Z}^n on the pseudo-data U^k , $k = 1, ..., n$, from test problem Poloni. The level lines \mathbb{Z}^C_α }
correspond in each case to α^* , 0.1, 0.2, 0.3 and 0.4

• In addition to One can model the Copula after having transformed each ; those which allows to each model the Pa variables with the respective CDF, different modelling options are shown here…

On the estimation of Pareto fronts from the point of view of copula theory

Mickaël Binois, Didier Rullière, Olivier Roustant

0

 $C : [0,1]^d \rightarrow [0,1]$ is d -dimensional copula if C is a joint cumulative distribution function of a d -dimensional random $\bm{\mid}$ vector on the unit cube $[0,1]^d$ with uniform marginals

Figure 13: Estimated level line $\partial L_{\alpha^*}^F$ for the Poloni test problem (green dashed line), compared to the Pareto front approximation from the observation P_n (black line) and the true Pareto front P (violet solid line). Other level lines with levels $0.1, 0.2, 0.3$ and 0.4 are also displayed with thinner lines.

Sklar theorem

For any continuous multivariate distribution function F_Y , there $ext{exists a 1}$ Gumbel copula RMSE = 0.0708 $F_Y(y_1,$

… which allows to estimate the level set and the Pareto front

Applications & use cases

Applications Hardware-aware NAS
• Hardware-aware NAS looks at finding architecture with good latency/accuracy tradeoffs…

- Hardware-aware NAS looks at finding architecture with good latency/accuracy tradeoffs…
- So that they can be deployed on device

- Hardware-aware NAS looks at finding architecture with good latency/accuracy tradeoffs…
- So that they can be deployed on device
- Perform search on each device

- Hardware-aware NAS looks at finding architecture with good latency/accuracy tradeoffs…
- So that they can be deployed on device
- Perform search on each device

- Hardware-aware NAS looks at finding architecture with good latency/accuracy tradeoffs…
- So that they can be deployed on device
- Perform search on each device

- Hardware-aware NAS looks at finding architecture with good latency/accuracy tradeoffs…
- So that they can be deployed on device
- Perform search on each device

• Hyperparameter and machine types can be tuned at the same time!

- Hyperparameter and machine types can be tuned at the same time!
- Add machine type (type/number of Cpu and Gpu \Rightarrow ~100 choices in AWS) to search space

- Hyperparameter and machine types can be tuned at the same time!
- Add machine type (type/number of Cpu and Gpu \Rightarrow ~100 choices in AWS) to search space
- Machines have different speed and cost trade-offs

- Hyperparameter and machine types can be tuned at the same time!
- Add machine type (type/number of Cpu and Gpu \Rightarrow ~100 choices in AWS) to search space
- Machines have different speed and cost trade-offs
-

Applications Multiobjective transfer learning

I

Applications Multiobjective transfer learning

Applications Multiobjective transfer learning

• $x \in \mathcal{X}$ space of models and hyperparameters

- $x \in \mathcal{X}$ space of models and hyperparameters
- $f(x) \in \mathbb{R}^d$ has d objectives (error, latency, fairness, ...) \cdot

- $x \in \mathcal{X}$ space of models and hyperparameters
- $f(x) \in \mathbb{R}^d$ has d objectives (error, latency, fairness, ...) \cdot
- Evaluating all options in $\mathscr X$ is too expensive!

- $x \in \mathcal{X}$ space of models and hyperparameters
- $f(x) \in \mathbb{R}^d$ has d objectives (error, latency, fairness, ...) \cdot
- Evaluating all options in $\mathscr X$ is too expensive!
- Given offline evaluations, can we approximate the Pareto Front in a zero-shot fashion?

- $x \in \mathcal{X}$ space of models and hyperparameters
- $f(x) \in \mathbb{R}^d$ has d objectives (error, latency, fairness, ...) \cdot
- Evaluating all options in $\mathscr X$ is too expensive!
- Given offline evaluations, can we approximate the Pareto Front in a zero-shot fashion?

Error and latency for time series forecasting models

• Assume we have access to offline evaluations...

• Assume we have access to offline evaluations…

- Assume we have access to offline evaluations…
- 1. Normalize each objective and task with $\psi = \Phi^{-1} \circ F$

- Assume we have access to offline evaluations…
- 1. Normalize each objective and task with $\psi = \Phi^{-1} \circ F$

- Assume we have access to offline evaluations…
- 1. Normalize each objective and task with $\psi = \Phi^{-1} \circ F$
- 2. Fit *d* independent predictive models for each objectives $[z_1(x), \ldots, z_d(x)]$

- Assume we have access to offline evaluations…
- 1. Normalize each objective and task with $\psi = \Phi^{-1} \circ F$
- 2. Fit *d* independent predictive models for each objectives $[z_1(x), \ldots, z_d(x)]$
- 3. Predict objectives on the new task on all untrained models

- Assume we have access to offline evaluations…
- 1. Normalize each objective and task with $\psi = \Phi^{-1} \circ F$
- 2. Fit *d* independent predictive models for each objectives $[z_1(x), \ldots, z_d(x)]$
- 3. Predict objectives on the new task on all untrained models

- Assume we have access to offline evaluations…
- 1. Normalize each objective and task with $\psi = \Phi^{-1} \circ F$
- 2. Fit *d* independent predictive models for each objectives $[z_1(x), \ldots, z_d(x)]$
- 3. Predict objectives on the new task on all untrained models

t objectives for configurations

- Assume we have access to offline evaluations…
- 1. Normalize each objective and task with $\psi = \Phi^{-1} \circ F$
- 2. Fit *d* independent predictive models for each objectives $[z_1(x), \ldots, z_d(x)]$
- 3. Predict objectives on the new task on all untrained models

latency

- Assume we have access to offline evaluations…
- 1. Normalize each objective and task with $\psi = \Phi^{-1} \circ F$
- 2. Fit *d* independent predictive models for each objectives $[z_1(x), \ldots, z_d(x)]$
- 3. Predict objectives on the new task on all untrained models
- 4. Return configuration on the Pareto front of predictions

t objectives for configurations

latency

- Assume we have access to offline evaluations…
- 1. Normalize each objective and task with $\psi = \Phi^{-1} \circ F$
- 2. Fit *d* independent predictive models for each objectives $[z_1(x), \ldots, z_d(x)]$
- 3. Predict objectives on the new task on all untrained models
- 4. Return configuration on the Pareto front of predictions

t objectives for configurations

latency

Multiobjective transfer learning Zeroshot prediction of Pareto front through transfer learning

Example of one zero-shot selection in a fixed task

Average performance on all tasks

Multiobjective transfer learning Zeroshot prediction of Pareto front through transfer learning

Example of one zero-shot selection in a fixed task

Average performance on all tasks

Multiobjective transfer learning Zeroshot prediction of Pareto front through transfer learning

Example of one zero-shot selection in a fixed task

Average performance on all tasks

Applications: Instance Recommendation

• Instance recommendation for model deployment

- Instance recommendation for model deployment
- Recommend endpoint configuration (machine type, number of OMP thread, …) given a ML model

- Instance recommendation for model deployment
- Recommend endpoint configuration (machine type, number of OMP thread, …) given a ML model
- Wants to optimise:

- Instance recommendation for model deployment
- Recommend endpoint configuration (machine type, number of OMP thread, …) given a ML model
- Wants to optimise:
	- **Latency**

- Instance recommendation for model deployment
- Recommend endpoint configuration (machine type, number of OMP thread, …) given a ML model
- Wants to optimise:
	- **Latency**
	- **Throughput**

- Instance recommendation for model deployment
- Recommend endpoint configuration (machine type, number of OMP thread, …) given a ML model
- Wants to optimise:
	- **Latency**
	- **Throughput**
	- Cost per hour

- Instance recommendation for model deployment
- Recommend endpoint configuration (machine type, number of OMP thread, …) given a ML model
- Wants to optimise:
	- **Latency**
	- **Throughput**
	- Cost per hour
- Ideally, wants to get recommendation eg zeroshot recommendations

Average time for 10000 batches (seconds)

DeepAR time vs cost for 10000 batch (2 layers, 40 cells)

m5: 4 CPUs machine c5.4x: 16 CPUs machine g4dn.16x: 64 CPUs machine with one GPU (T4) p3.2x: 8 CPU machines with V100 GPU If we have some metadata on the model being used (reset, XGboost, …). Can we predict the Pareto front of hardware configurations?

-
-
-
-
-
-
-
-
- -

I have an **XGBoost model, what** machine should I use to deploy it?

UU

• Sample many ML model and measure latency and cost on multiple machine

I have an XGBoost model, what machine should I use to deploy it?

- Sample many ML model and measure latency and cost on multiple machine
- Build a predictive model $\Phi_{\theta}(x,m) \in \mathbb{R}^2$ that predicts the latency and cost of the model on a machine m given metadata x $\Phi_{\theta}(x, m) \in \mathbb{R}^2$

- Sample many ML model and measure latency and cost on multiple machine
- Build a predictive model $\Phi_{\theta}(x,m) \in \mathbb{R}^2$ that predicts the latency and cost of the model on a machine m given metadata x $\Phi_{\theta}(x, m) \in \mathbb{R}^2$
- Metadata contains features such as the framework type (Pytorch, XGBoost, ...)

- Sample many ML model and measure latency and cost on multiple machine
- Build a predictive model $\Phi_{\theta}(x,m) \in \mathbb{R}^2$ that predicts the latency and cost of the model on a machine m given metadata x $\Phi_{\theta}(x, m) \in \mathbb{R}^2$
- Metadata contains features such as the framework type (Pytorch, XGBoost, ...)

Predict latency and cost for each machine type given metadata *x* using $\Phi_{\theta}(x, m) \in \mathbb{R}^2$

- Sample many ML model and measure latency and cost on multiple machine
- Build a predictive model $\Phi_{\theta}(x,m) \in \mathbb{R}^2$ that predicts the latency and cost of the model on a machine m given metadata x $\Phi_{\theta}(x, m) \in \mathbb{R}^2$
- Metadata contains features such as the framework type (Pytorch, XGBoost, ...)

Predict latency and cost for each machine type given metadata *x* using $\Phi_{\theta}(x, m) \in \mathbb{R}^2$

 $cost$

- Sample many ML model and measure latency and cost on multiple machine
- Build a predictive model $\Phi_{\theta}(x,m) \in \mathbb{R}^2$ that predicts the latency and cost of the model on a machine m given metadata x $\Phi_{\theta}(x, m) \in \mathbb{R}^2$
- Metadata contains features such as the framework type (Pytorch, XGBoost, ...)

Predict latency and cost for each machine type given metadata *x* using $\Phi_{\theta}(x, m) \in \mathbb{R}^2$

 $cost$

- Sample many ML model and measure latency and cost on multiple machine
- Build a predictive model $\Phi_{\theta}(x,m) \in \mathbb{R}^2$ that predicts the latency and cost of the model on a machine m given metadata x $\Phi_{\theta}(x, m) \in \mathbb{R}^2$
- Metadata contains features such as the framework type (Pytorch, XGBoost, ...)

Predict latency and cost for each machine type given metadata *x* using $\Phi_{\theta}(x, m) \in \mathbb{R}^2$

 $cost$

- Sample many ML model and measure latency and cost on multiple machine
- Build a predictive model $\Phi_{\theta}(x,m) \in \mathbb{R}^2$ that predicts the latency and cost of the model on a machine m given metadata x $\Phi_{\theta}(x, m) \in \mathbb{R}^2$
- Metadata contains features such as the framework type (Pytorch, XGBoost, ...)

- Sample many ML model and measure latency and cost on multiple machine
- Build a predictive model $\Phi_{\theta}(x,m) \in \mathbb{R}^2$ that predicts the latency and cost of the model on a machine m given metadata x $\Phi_{\theta}(x, m) \in \mathbb{R}^2$
- Metadata contains features such as the framework type (Pytorch, XGBoost, ...)

-
-
-
-
-
-
-

• Evaluating LLMs is expensive $\frac{1}{3}$

-
-
-
-
-
-
-

- Evaluating LLMs is expensive \bullet
- It costs ~3500\$ to evaluate one model on [Chatbot Arena](https://chat.lmsys.org/) with human annotations…

- Evaluating LLMs is expensive ϵ
- It costs ~3500\$ to evaluate one model on [Chatbot Arena](https://chat.lmsys.org/) with human annotations…
- To get an leaderboard of ELO ratings

- Evaluating LLMs is expensive ϵ
- It costs ~3500\$ to evaluate one model on [Chatbot Arena](https://chat.lmsys.org/) with human annotations…
- To get an leaderboard of ELO ratings
- Can we get a cheaper approximation?

- Evaluating LLMs is expensive ϵ
- It costs ~3500\$ to evaluate one model on [Chatbot Arena](https://chat.lmsys.org/) with human annotations…
- To get an leaderboard of ELO ratings
- Can we get a cheaper approximation?

- Evaluating LLMs is expensive ϵ
- It costs ~3500\$ to evaluate one model on [Chatbot Arena](https://chat.lmsys.org/) with human annotations…
- To get an leaderboard of ELO ratings
- Can we get a cheaper approximation?

• Cheaper alternative use LLM as a judge

• Cheaper alternative use LLM as a judge

• **System prompt**: You're an LLM that evaluates the strength of other LLMs, please evaluate the two options provided carefully and answer which of model A or B is better.

• Cheaper alternative use LLM as a judge

- **System prompt**: You're an LLM that evaluates the strength of other LLMs, please evaluate the two options provided carefully and answer which of model A or B is better.
- **Instruction**: What is the minimum broadband upload speed to stream at 720p 30fps to twitch while playing an online videogame? Twitch recommends 3000kbps upload speed in my streaming software, but how much extra headroom do I need so the twitch stream and online gameplay are both smooth?

• Cheaper alternative use LLM as a judge

- **System prompt**: You're an LLM that evaluates the strength of other LLMs, please evaluate the two options provided carefully and answer which of model A or B is better.
- **Instruction**: What is the minimum broadband upload speed to stream at 720p 30fps to twitch while playing an online videogame? Twitch recommends 3000kbps upload speed in my streaming software, but how much extra headroom do I need so the twitch stream and online gameplay are both smooth?
- **Model A**: Streaming on Twitch at 720p 30fps with a bitrate of 3000kbps (kilobits per second) is within the recommended settings
• Cheaper alternative use LLM as a judge

- **System prompt**: You're an LLM that evaluates the strength of other LLMs, please evaluate the two options provided carefully and answer which of model A or B is better.
- **Instruction**: What is the minimum broadband upload speed to stream at 720p 30fps to twitch while playing an online videogame? Twitch recommends 3000kbps upload speed in my streaming software, but how much extra headroom do I need so the twitch stream and online gameplay are both smooth?
- **Model A**: Streaming on Twitch at 720p 30fps with a bitrate of 3000kbps (kilobits per second) is within the recommended settings
- **Model B**: To stream at 720p 30fps to Twitch while playing an online videogame, you'll need to consider the upload speed requirements…

• Cheaper alternative use LLM as a judge

- **System prompt**: You're an LLM that evaluates the strength of other LLMs, please evaluate the two options provided carefully and answer which of model A or B is better.
- **Instruction**: What is the minimum broadband upload speed to stream at 720p 30fps to twitch while playing an online videogame? Twitch recommends 3000kbps upload speed in my streaming software, but how much extra headroom do I need so the twitch stream and online gameplay are both smooth?
- **Model A**: Streaming on Twitch at 720p 30fps with a bitrate of 3000kbps (kilobits per second) is within the recommended settings
- **Model B**: To stream at 720p 30fps to Twitch while playing an online videogame, you'll need to consider the upload speed requirements…
- **Best model** (must be A or B):

• Cheaper alternative use LLM as a judge

- **System prompt**: You're an LLM that evaluates the strength of other LLMs, please evaluate the two options provided carefully and answer which of model A or B is better.
- **Instruction**: What is the minimum broadband upload speed to stream at 720p 30fps to twitch while playing an online videogame? Twitch recommends 3000kbps upload speed in my streaming software, but how much extra headroom do I need so the twitch stream and online gameplay are both smooth?
- **Model A**: Streaming on Twitch at 720p 30fps with a bitrate of 3000kbps (kilobits per second) is within the recommended settings
- **Model B**: To stream at 720p 30fps to Twitch while playing an online videogame, you'll need to consider the upload speed requirements…
- **Best model** (must be A or B):

• Cheaper alternative use LLM as a judge

- **System prompt**: You're an LLM that evaluates the strength of other LLMs, please evaluate the two options provided carefully and answer which of model A or B is better.
- **Instruction**: What is the minimum broadband upload speed to stream at 720p 30fps to twitch while playing an online videogame? Twitch recommends 3000kbps upload speed in my streaming software, but how much extra headroom do I need so the twitch stream and online gameplay are both smooth?
- **Model A**: Streaming on Twitch at 720p 30fps with a bitrate of 3000kbps (kilobits per second) is within the recommended settings
- **Model B**: To stream at 720p 30fps to Twitch while playing an online videogame, you'll need to consider the upload speed requirements…
- **Best model** (must be A or B):

"A"

• Cheaper alternative use LLM as a judge

- **System prompt**: You're an LLM that evaluates the strength of other LLMs, please evaluate the two options provided carefully and answer which of model A or B is better.
- **Instruction**: What is the minimum broadband upload speed to stream at 720p 30fps to twitch while playing an online videogame? Twitch recommends 3000kbps upload speed in my streaming software, but how much extra headroom do I need so the twitch stream and online gameplay are both smooth?
- **Model A**: Streaming on Twitch at 720p 30fps with a bitrate of 3000kbps (kilobits per second) is within the recommended settings
- **Model B**: To stream at 720p 30fps to Twitch while playing an online videogame, you'll need to consider the upload speed requirements…
- **Best model** (must be A or B):

• Use fix baseline for model A (typically GPT4)

• Cheaper alternative use LLM as a judge

- **System prompt**: You're an LLM that evaluates the strength of other LLMs, please evaluate the two options provided carefully and answer which of model A or B is better.
- **Instruction**: What is the minimum broadband upload speed to stream at 720p 30fps to twitch while playing an online videogame? Twitch recommends 3000kbps upload speed in my streaming software, but how much extra headroom do I need so the twitch stream and online gameplay are both smooth?
- **Model A**: Streaming on Twitch at 720p 30fps with a bitrate of 3000kbps (kilobits per second) is within the recommended settings
- **Model B**: To stream at 720p 30fps to Twitch while playing an online videogame, you'll need to consider the upload speed requirements…
- **Best model** (must be A or B):

• Use fix baseline for model A (typically GPT4)

• Report win rate for all methods

• Cheaper alternative use LLM as a judge

- **System prompt**: You're an LLM that evaluates the strength of other LLMs, please evaluate the two options provided carefully and answer which of model A or B is better.
- **Instruction**: What is the minimum broadband upload speed to stream at 720p 30fps to twitch while playing an online videogame? Twitch recommends 3000kbps upload speed in my streaming software, but how much extra headroom do I need so the twitch stream and online gameplay are both smooth?
- **Model A**: Streaming on Twitch at 720p 30fps with a bitrate of 3000kbps (kilobits per second) is within the recommended settings
- **Model B**: To stream at 720p 30fps to Twitch while playing an online videogame, you'll need to consider the upload speed requirements…
- **Best model** (must be A or B):

• Use fix baseline for model A (typically GPT4)

• Report win rate for all methods

- LLM judge has **many** hyperparameters!
- LLM model (llama3-70B, llama3-8B, GPT4)
- Prompt being used
- Judge LLM inference parameters (temperature & topk)
- Number of LLM samples
- Float precision (FP8, BF16, …)
- Number of instructions evaluated

• Cheaper alternative use LLM as a judge

- **System prompt**: You're an LLM that evaluates the strength of other LLMs, please evaluate the two options provided carefully and answer which of model A or B is better.
- **Instruction**: What is the minimum broadband upload speed to stream at 720p 30fps to twitch while playing an online videogame? Twitch recommends 3000kbps upload speed in my streaming software, but how much extra headroom do I need so the twitch stream and online gameplay are both smooth?
- **Model A**: Streaming on Twitch at 720p 30fps with a bitrate of 3000kbps (kilobits per second) is within the recommended settings
- **Model B**: To stream at 720p 30fps to Twitch while playing an online videogame, you'll need to consider the upload speed requirements…
- **Best model** (must be A or B):

• Use fix baseline for model A (typically GPT4)

• Report win rate for all methods

- LLM judge has **many** hyperparameters!
- LLM model (llama3-70B, llama3-8B, GPT4)
- Prompt being used
- Judge LLM inference parameters (temperature & topk)
- Number of LLM samples
- Float precision (FP8, BF16, …)
- Number of instructions evaluated
- … and **multiple** objectives
- Spearman correlation with ELO ratings
- Dollar cost to evaluate a model

Table 1. Separability and agreement per benchmark.

Table 1. Separability and agreement per benchmark.

a maaala tilam cualaas in dua cual aid alga pilaaniraa

 $\triangleright \times$ Rest... \cup

Table 1. Separability and agreement per benchmark.

Judge

 $*ResL$

Azim difficulties to overcome Evaluating one judge configurations is too expensive (10\$ \times #models \sim 400\$)

Ideal case for multi-objective optimization!

Two techniques: subselect most informative instructions and use multifidelity

 $Cost($)$

Ilm

- gpt-4o
- meta-Ilama/Llama-3-70b-chat-hf
- meta-Ilama/Llama-3-8b-chat-hf
- gpt-3.5-turbo-0125
- gpt4-turbo

 $Cost($ \$)

Code and libraries

Code Some multiobjective libraries

 $\mathscr{O}^- \equiv$ **CO** README GPareto GPareto: Gaussian Processes for Pareto Front Estimation and Optimization This R package provides tools for multi-objective optimization of expensive black-box functions along with estimation of Pareto fronts. Installation For the stable version: http://cran.r-project.org/package=GPareto

This the development version, contributions are welcomed.

For the stable version: http://cran.r-project.org/package=GPareto

This the development version, contributions are welcomed.

For the stable version: http://cran.r-project.org/package=GPareto

This the development version, contributions are welcomed.

PyTorch.

For the stable version: http://cran.r-project.org/package=GPareto

This the development version, contributions are welcomed.

Welcome to PyGMO

PyGMO (the Python Parallel Global Multiobjective Optimizer) is a scientific library providing a large number of optimisation problems and algorithms under the same powerful parallelization abstraction built around the generalized island-model paradigm. What this means to the user is that the available algorithms are all

Code Some multiobjective libraries

- General python library
- Contains optimizers but also utilities to compute
- Hypervolume, Hypervolume contribution, …
- Contains approximation algorithms

Welcome to PyGMO

PyGMO (the Python Parallel Global Multiobjective Optimizer) is a scientific library providing a large number of optimisation problems and algorithms under the same powerful parallelization abstraction built around the generalized island-model paradigm. What this means to the user is that the available algorithms are all

Code

How to tune multiple objectives in Syne Tune

Step 1: report multiple objectives in a training script

```
if __name__ == "__main__":
# plot_function()
parser = ArgumentParser()parser.add_argument("--steps", type=int, required=True)
parser.add_argument("--theta", type=float, required=True)
parser.add_argument("--sleep_time", type=float, required=False, default=0.1)
args, \_ = \text{parse} \_known_args()
assert 0 \leq \arg s. theta \leq np. pi / 2
reporter = Reporter()for step in range(args.steps):
    y = f(t=step, theta=args.theta)reporter(step=step, **y)
```
https://github.com/syne-tune/syne-tune/blob/main/examples/launch_height_moasha.py

Code

How to tune multiple objectives in Syne Tune

```
Step 1: report multiple objectives in a training script Step 2: call a multiobjective optimizer to tune the training script
                                                                                             entry\_point = (if _name_ = = "main_":
                                                                                                Path(file_).parent
# plot_function()
                                                                                                / "training_scripts"
                                                                                                / "mo_artificial"
parser = ArgumentParser()/ "mo_artificial.py"
parser.add_argument("--steps", type=int, required=True)
parser.add_argument("--theta", type=float, required=True)
                                                                                             mode = "min"parser.add_argument("--sleep_time", type=float, required=False, default=0.1)
                                                                                             np.randomseed(0)args, \_ = \text{parse} \_known_args()
                                                                                             scheduler = MOASHA(
                                                                                                max_t=max_steps,
assert 0 \leq a rgs. theta \leq np. pi / 2
                                                                                                time_attr="step",
                                                                                                mode=mode,
reporter = Reporter()metrics=["y1", "y2"],
for step in range(args.steps):
                                                                                                config_space=config_space,
    y = f(t=step, theta=args.theta)trial_backend = LocalBackend(entry_point=str(entry_point))
     reporter(\text{step=step}, **y)stop_criterion = StoppingCriterion(max_walloc\_color_time=20)tuner = Tuner(trial_backend=trial_backend,
                                                                                                scheduler=scheduler,
                                                                                                stop_criterion=stop_criterion,
                                                                                                n_workers=n_workers,
                                                                                                sleep_time=0.5,
                                                                                             tuner.run()
```
https://github.com/syne-tune/syne-tune/blob/main/examples/launch_height_moasha.py

-
-
-
-
-
-
-
-
- -
- - -
		-
		-
	-
- -
	-
- -
	-
	-
-
-
-
-
-
-
-
-
-
- -
	-
	-
-
- - -
		- -
- -
	-
	-
	-
	-
	-
	-
- -
	-
	- -
- -
	-
-
-
-

• Multiobjective optimization allows to optimise multiple objectives at the same time

-
-

-
-
- Key methods:

-
-
- Key methods:
	- Scalarization

-
-
- Key methods:
	- Scalarization
	- Bayesian Optimization

-
-
- Key methods:
	- Scalarization
	- Bayesian Optimization
	- Evolution Algorithms
Conclusion

-
-
- Key methods:
	- Scalarization
	- Bayesian Optimization
	- Evolution Algorithms
- Many applications!

• Multiobjective optimization allows to optimise multiple objectives at the same time • Generally not a single solution but a set of optimal solutions, the Pareto front

Conclusion

• Multiobjective optimization allows to optimise multiple objectives at the same time • Generally not a single solution but a set of optimal solutions, the Pareto front

-
-
- Key methods:
	- Scalarization
	- Bayesian Optimization
	- Evolution Algorithms
- Many applications!
- Active area of research